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# Logic and Constraint Programming

PROLOG

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The *list* is a simple data structure widely used in non-numeric programming.

A sequence list is a sequence of any number of items, such as: [ann, tennis, tom, skiing]

Remember: all structured objects in Prolog are trees. Lists are no exception to this.

A list can be empty or non-empty.

Empty: [].

Non-Empty:

the first items is called the *head* of the list;
 the remaining part of the list is called the *tail*.







The tail has to be a list. The head and the tail are combined into a structure by the functor ".":

.( Head, Tail)

Since Tails is in turn a list, it is either empty or it has its own head and tail





#### **Operations on lists**



**Membership** relation. Checking whether some object is an element of a list

Concatenation of two lists, obtaining a third one

Adding a new object to a list, or **deleting** an object from it.

## Sublist



Let us define the sublist relation such that:

sublist([c,d,e], [a,b,c,d,e,f])is truesublist([c,e], [a,b,c,d,e,f])is false

S is a sublist of L if: 1. L can be decomposed into two lists, L1 and L2, and 2. L2 can be decomposed into two lists, S and some L3.

```
sublist( S, L) :-
conc( L1, L2, L),
conc( S, L3, L2).
```

What if we ask **sublist( S, [a,b,c] )**?

#### Permutation



We can generate permutations of a list through backtracking using the **permutation** procedure, as in the following:

```
?- permutation( [a,b,c], P).
```

?- random\_permutation( [a,b,c], P).

```
P = [a, b, c] ;
P = [a, c, b] ;
P = [b, a, c] ;
P = [b, c, a] ;
P = [c, a, b] ;
P = [c, b, a] ;
false.
```

## List length



Let us count the elements in a list List and instantiate N to thein number.

1. If the list is empty then its length is 0

2. If the list is not empty then **List = [Head | Tail]**; then its length is equal to 1 plus the length of the tail **Tail** 

length( [ ], 0).	?- length([ a,b, [ c,d], e], N).
length([_   Tail], N) :- length( Tails, N1),	N = 4
N is 1 + N1.	

ERROR: /Users/fabriziofornari/Desktop/LCP – Fabrizio Fornari/SWI–Prolog/PROGRAMS/list8.pl:33: ERROR: No permission to modify static procedure `length/2' ERROR: Defined at /Applications/SWI–Prolog.app/Contents/swipl/boot/init.pl:4056

## SWI-Prolog library



https://www.swi-prolog.org/pldoc/man?section=libpl

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### Let us define some relations

max(X, Y, Max) so that Max is the greater of two numbers X and Y.

max( X, Y, X) :-X >= Y.

max( X, Y, Y) :-Y > X.



maxlist( List, Max) so that Max is the greatest number in the list of numbers denoted by List.

```
maxlist([X],X).
```

% Maximum of single-element list

```
maxlist([X, Y | Rest], Max) :-
maxlist( [Y| Rest ], MaxRest),
max( X, MaxRest, Max).
```

% At least two elements in list

% Max is the greater of X and MaxRest



maxlist( List, Max) so that Max is the greatest number in the list of numbers denoted by List.

Which is the execution trace of maxlist([3, 7, 2, 10], MaxRest)



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mas (2, 10, Moskert') max (7, Mos Ret', Mos Ret), max (3, Mos Ret, Max) mas (2, 10, Mas Ret') 178 8 7=7 27=10 Jelse 1072 true



max (3, 10, 16x) 478 メフニク 1073 1 Mar = 10 37=10 folk

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## Let us define some relations

**?- trace.** [trace] ?- maxlist([3,7,2,10], Max).

Call: (10) maxlist([3, 7, 2, 10], \_19236) ? creep Call: (11) maxlist([7, 2, 10], \_20488) ? creep Call: (12) maxlist([2, 10], \_21250) ? creep Call: (13) maxlist([10], \_22012) ? creep Exit: (13) maxlist([10], 10) ? creep

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max (3, 10, 16x) 478 37=10 10x=16 file

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Define the predicate ordered(List)

which is true if **List** is an ordered list of numbers such as

ordered([ 2, 3, 7, 10]).

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```
ordered([ 2, 3, 7, 10]).
```

ordered([X]). % A single-element list is ordered

```
ordered([X,Y|Rest]) :-
X =< Y,
ordered([Y|Rest]).
```





2\*a + b\*c infix

+( \*(2,a), \*(b,c) ) In Prolog



A programmer can define his or her own operators. peter has information. floor supports table.

These facts are exactly equivalent to: has( peter, information). supports( floor, table).





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These facts are exactly equivalent to: has( peter, information). supports( floor, table).







Operators are normally used, as functors, only to combine objects into structures and not to invoke actions on data.

Operator names are atoms. An operator's precedence must be in some range which depends on the implementation. We can assume a range between 1 and 1200.



If an argument is enclosed in parentheses or it in an unstructured object then its precedence is 0; if an argument is a sctucture then its precedence is equal to the precedence of its principal functor.

Three groups of operator types:

- infix operators of three types: xfx xfy yfx
   prefix operators of two types: fx fy
- 3. postfix operators of two types: **xf yf**

"x" represents an argument whose precedence <u>must be strictly lower</u> than that of the operator.

"y" represents an argument whose precedence is lower or equal to that of the operator.



It helps to disambiguate expressions with several operators of the same precedence.

 $\mathbf{a} - \mathbf{b} - \mathbf{c}$  is normally understood as  $(\mathbf{a} - \mathbf{b}) - \mathbf{c}$  and not as  $\mathbf{a} - (\mathbf{b} - \mathbf{c})$ .

The operator "-" to achieve the normal interpretation has to be defined as yfx





Another example with the prefix operator **not**:

#### not not p

is legal if **not** is defined as **fy**; it is illegal if defined as **fx** because the argument to the first **not** is **not p**, which has the same precedence as **not** itself.

In this case the expression has to be written with parentheses:

#### not( not p)

Some operators in the Prolog system are already defined. What they are and their precedence depends on the specific implementation of Prolog. https://www.swi-prolog.org/pldoc/man?section=operators



The use of operators can greatly improve the readability of programs.

If we want to state one of de Morgan's equivalence theorems written as:

$$\sim$$
(A & B) <==>  $\sim$ A  $\vee \sim$ B

One way is:

#### equivalence(not(and(A, B)), or(not(A), not(B))).

It is a good programming practice to try to retain as much resemblance as possible between the original problem notation and the notation used in the program



#### equivalence( not( and( A, B)), or( not( A), not( B) ) ).

We can define operators such as:

- :- op( 800, xfx, < = = = >).
  :- op( 700, xfy, v).
  :- op( 600, xfy, &).
  :- op( 500, fy, ~).
- % Logical equivalence
  % Disjunction
  % Conjunction
  % Negation

And write the de Morgan's theorem as:

$$\sim$$
(A & B) < = = = >  $\sim$ A v  $\sim$ B.

A lot similar to:  $\sim$ (A & B) < ===>  $\sim$ A  $\lor \sim$ B

Instead of: equivalence( not( and( A, B)), or( not( A), not( B) ) ).



How can we visualize the tree structure?

### Arithmetic



Some of the predefined operators can be used for basic arithmetic operations.

- + addition
- subtraction
- multiplication
- / division
- \*\* power
- // integer division
- mod modulo, the remainder of integer division

Try asking Prolog:?-X = 1 + 2.Try asking Prolog: $?-X ext{ is 5/2}$ , $?-Y ext{ is 5//2}$ , $?-X ext{ is 1 + 2}$ . $?-Z ext{ is 5 mod 2}$ .

Try asking Prolog: ?- 277 \* 37 > 10000.

#### Arithmetic



are equal

are not equal

?- 1 + A = B + 2. A = 2, B = 1.

### Arithmetic



Suppose we have a relation **born** that relates the names of people with their birth years. We could retrieve the names of people born between 1980 and 1990 inclusive with the followin question:

?- born( Name, Year), Year >= 1980, Year =< 1990.



- :- op( 300, xfx, plays).
- :- op( 200, xfy, and).

Then the following two terms are syntactically legal objects: Term1 = jimmy plays football and squash Term2 = susan plays tennis and basketball and volleyball

How are these terms understood by Prolog? What are their principal functors and what is theirs structure?

Term1 = plays( jimmy, and( football, squash ) ) Term2 = plays (susan, and( tennis, and( basketball, volleyball ) ) )

## Summary



The list is a frequently used structure. It is either empty or consists of a *head* and a *tail* which is alist as well. Prolog provides a special notation for lists.

Common operations on lists, programmed in this chapter, are: list membership, concatenation, adding an item, deleting an item, sublist.

The *operator notation* allows the programmer to tailor the syntax of programs toward particular needs. Using operators the redability of programs can be greatly improved.

## Summary



New operators are defined by the directive **op**, standing the name of an operator, its type and precedence.

In principle, there is no operation associated with an operator; operators are merely a syntactic device providing an alternative syntax for terms.

Arithmetic is done by built-in procedures. Evaluation of an arithmetic expression is forced by the procedure **is** and by the copmarison predicates <, =<, etc.

Graph structures are useful abstract representation for many problems.

Directed graph





Graph structures are useful abstract representation for many problems.

Directed graph



link( a, b).	link( a, c).
link( b, d).	link( c, d).
link( c, f).	link( d, e).
link( d, f).	link( f, a).



Graph structures are useful abstract representation for many problems.

Directed graph



link( a, b).	link( a, c).
link( b, d).	link( c, d).
link( c, f).	link( d, e).
link( d, f).	link( f, a).

Which is the most common type of question concerning a graph?

Is there a path from node X to node Y? And if there is, show the path.

Concrete practical questions are:

- How can I travel from Camerino to Rome?
- How can a user navigate from web page X to page Y?
- How many links of the type 'P1 knows P2' in a social network are needed to get from any person in the world to any other person, by following a chain of 'knows' links between people?

All these concrete questions can be answered by the same algorithms that work on abstract graphs where nodes and links have no concrete meaning



people in the United States.





Graph structures are useful abstract representation for many problems.

link( a,b). link( a,c). link( b,d). link( c,d). link( c,f). link( d,e). link( d,f). link( f,a).



e

link( a, b).	link( a, c).
link( b, d).	link( c, d).
link( c, f).	link( d, e).
link( d, f).	link( f, a).



#### path( StartNode, EndNode)

it is true if there exists a path from StartNode to EndNote in the given graph.

When does a path exists from StartNode to EndNote?

- A path exists if
- 1. StartNode and EndNode are both the same node, or
- 2. there is a link from StartNode to NextNode, and there is a path from NextNode to EndNode

How can we write these two rules in Prolog?

path(Node, Node). % StartNode and EndNode are both the same node

path( StartNode, EndNode) :link( StartNode, NextNode), path( NextNode, EndNode).



path(Node, Node). % StartNode and EndNode are both the same node

path( StartNode, EndNode) :link( StartNode, NextNode), path( NextNode, EndNode).

?- path(a,e).

true

?- path(a,X).

What are we asking?



path(Node, Node). % StartNode and EndNode are both the same node

path( StartNode, EndNode) :link( StartNode, NextNode), path( NextNode, EndNode).

?- path(a,e).

true

?- path(a,X).

Which are the nodes X reachable from a?

?- path(a,X).

Which are the nodes X reachable from **a**?



link( a, b).	link(a, c).
link( b, d).	link( c, d).
link( c, f).	link( d, e).
link( d, f).	link( f, a).

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What happens?

X = a;

X = b ;

X = d;

X = e;

X = f;

X = a;

X = b ;

Prolog has found that a is connected to a itself,
b, d, e, f. Then it is back to a restarting the cycle.

It will never find that **a** is linked to **c**, **link( a**,**c)**.

Let us ask **?- path( a,c).** 

?- path( a,c).
ERROR: Stack limit (1.0Gb) exceeded
ERROR: Stack sizes: local: 0.8Gb, global: 0.1Gb, trail: 28.7Mb
ERROR: Stack depth: 15,048,885, last-call: 75%, Choice points: 3,762,22
ERROR: Possible non-terminating recursion:
ERROR: [15,048,885] user:path(e, c)
<b>FRROR</b> : [15,048,884] user: $path(d, c)$

Why does it happen?

Which is the execution trace?

?- path( a,c).

link( a,b). link( a,c). link( b,d). link( c,d). link( c,f). link( d,e). link( d,f). link( f,a).



path(Node, Node).

path( StartNode, EndNode) :link( StartNode, NextNode), path( NextNode, EndNode).





The execution trace of **?- path( a,c)**.

path (Stort Node, End Node) link (a, Next), foth (Next, c) Next = b link (a,b)

link (a,b), link (b, Nest'), both (Nest', C) Next = a link (a,b), link (b,d),



link (a,b), Nest"= e link (b, d), link (d, Nest"), path (Next", c) link (a, b), link (b,d), link (d, e), path (e, c)

link (a,b), link (b, d), link (d, e), link (e, Nest"), false, no fact about link (e, X) poth (Nest", c)



link (a,b), link (b, d), link (d, Next") foth (Next",c) Nest"= \$ link (a, b), link (b, d), link (d, f),

link (a,b), link (b, d), link (d, f), link (f, Nest") poth (Nest", c) Nest"=a link (a, b), link (b, d), link (d, f), link (f, a), link (a, Mest"") foth (Mest"", C



The style in which our program searches a graph is called *depht-first*. Whenever there is a choice between alternatives where to continue the search, the program chooses a current deepest alternative.

Each recursive call takes some memory, that is why Prolog eventually runs out of memory. Because Prolog has to remember where to return in the event that backtracking occurs.

Our simple program with DFS (Depth-First Search), has a problem. The problem does not occur when the graph to be searched is finite and has no cyclical path.

The problem can be fixed in many ways, for example by limiting the depth of search, or by checking for node repetition on the currently expanded path.