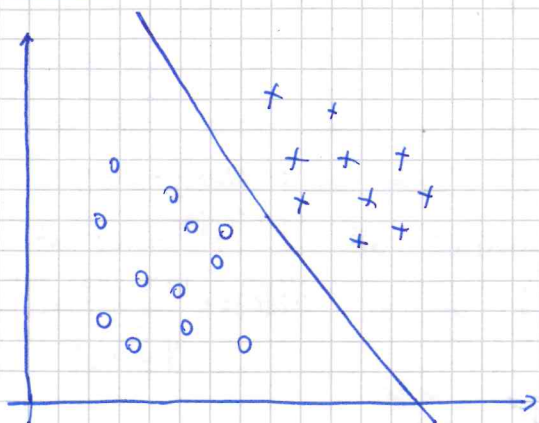


# SVM



## CLASSIFICATION TASK

$$y = \{x, 0\}$$

$$y = ax + q = \theta_0 + \theta_1 x$$

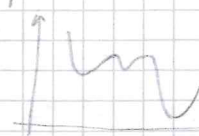
$$q = \theta_0$$

$$a = \theta_1$$

Ribadire che la funzione  
convessa non solo  
quella



e quella



non sono convexe

(se posso vedere posizioni  
dei due suoi costanti  
in intervalli.)

SGD? spigolo here

In general we want to find an hyperplane  $H = \{x \in \mathbb{R}^n \mid \bar{x}^T \bar{\theta} = 0\}$

In SVM we want to find a couple of hyperplanes such that

- 1) they are parallel and they separate the two classes
- 2) the distance between the two hyperplanes is the maximum distance

### • DATA SET LINEARLY SEPARABLE

$$\bar{x} \in \mathbb{R}^n, y \in \{+1, -1\}$$

Let's suppose that exists an hyperplane ~~convex~~  $\bar{w}^T \bar{x} + \theta > 0$

if  $y = 1$  and  $\bar{w}^T \bar{x} + \theta < 0$  if  $y = -1 \Rightarrow$

(The data set is linearly separable)

It is possible to prove that the previous condition is satisfied if and only if

$$\hat{w}^T \bar{x} + \hat{\theta} \geq 1, y = 1$$

and

$$\hat{w}^T \bar{x} + \hat{\theta} \leq -1, y = -1$$

$\rightarrow$  N.B.: we will use  $w$  instead of  $\hat{w}$  and  $\theta$  instead of  $\hat{\theta}$

USING A SET OF OUR POINT (TRAINING SET) we want to determine

$w$  and  $\theta$  for any point  $\bar{x}$

(The dimension of the dataset is  $N$ ) such that

$$y_i (\bar{w}^T \bar{x}_i + \theta) \geq 1 \quad \text{for all } \bar{x}_i \quad i = 1, \dots, N$$

Moreover the distance between the two hyperplanes has to be the maximum distance

So we consider  $H$ ,  $H_+$  and  $H_-$  as three parallel hyperplanes

$$H = \{ \bar{x} \in \mathbb{R}^d : \bar{w}^T \bar{x} + \theta = 0 \}$$

$$H_+ = \{ \bar{x} \in \mathbb{R}^d : \bar{w}^T \bar{x} + \theta = 1 \}$$

$$H_- = \{ \bar{x} \in \mathbb{R}^d : \bar{w}^T \bar{x} + \theta = -1 \}$$

$$r: ax+by+c=0$$

$$P(x_p, y_p)$$

$$d(P, r) = \frac{|ax_p + by_p + c|}{\sqrt{a^2 + b^2}}$$

if  $\bar{x} \in H_+$

$$\text{dist}(x, H_+) = \frac{|\bar{w}^T \bar{x} + \theta|}{\|\bar{w}\|} = \frac{1}{\|\bar{w}\|}$$

if  $\bar{x} \in H_-$

$$\text{dist}(x, H_-) = \frac{|\bar{w}^T \bar{x} + \theta|}{\|\bar{w}\|} = \frac{1}{\|\bar{w}\|}$$

$$\text{So } \text{dist}(H_+, H_-) = \frac{2}{\|\bar{w}\|}$$

In the TRAINING phase we need to solve the following problem

$$\min_{(w, \theta)} \frac{1}{2} \bar{w}^T \bar{w}$$

(\*)

$$\text{subject to } y_i (\bar{w}^T \bar{x}_i + \theta) \geq 1, \quad i=1, \dots, N$$

Obtained the optimal  $w^*$  and  $\theta^*$  we can write the ~~classifier~~ CLASSIFIER as

$$h(x) = \text{sign}(f(x)) = \begin{cases} 1 & , \text{ if } f(x) > 0 \\ -1 & , \text{ if } f(x) < 0 \end{cases}$$

$$f(x) = \bar{w}^T \bar{x} + \theta$$

• DATA SET NOT LINEARLY SEPARABLE

Actually, in real problems the data are not linearly separable and in this case there is no solution for the problem (\*)

For this reason we need to modify that problem, introducing the possibility for the training data to be misclassified

The new problem is the following

$$\begin{aligned} \min_{w, \sigma, \xi} \quad & \frac{1}{2} \bar{x}^T w + C \sum_{i=1}^N \xi_i \\ \text{subject to} \quad & y_i (\bar{w}^T x_i + \sigma) \geq 1 - \xi_i, \quad i = 1, \dots, N \\ & \xi_i \geq 0, \quad i = 1, \dots, N \end{aligned}$$

- $\frac{1}{2} \bar{w}^T \bar{w}$  controls the "ability" to learn of the system, maximizing the distance  $\text{dist}(H_+, H_-)$
- $\bar{e}^T \xi$  controls the misclassification,  $C$  penalizes the misclassified data.

$$\bar{e}^T = [1, 1, \dots, 1] \in \mathbb{R}^N$$

Actually instead of solving the previous minimization problem we solve the, so called, DUAL PROBLEM

$$\begin{aligned} \min_{\alpha} \quad & \frac{1}{2} \bar{\alpha}^T Q \bar{\alpha} - \bar{e}^T \bar{\alpha} \\ \text{subject to} \quad & \bar{y}^T \bar{\alpha} = 0 \\ & 0 \leq \alpha \leq C \end{aligned}$$

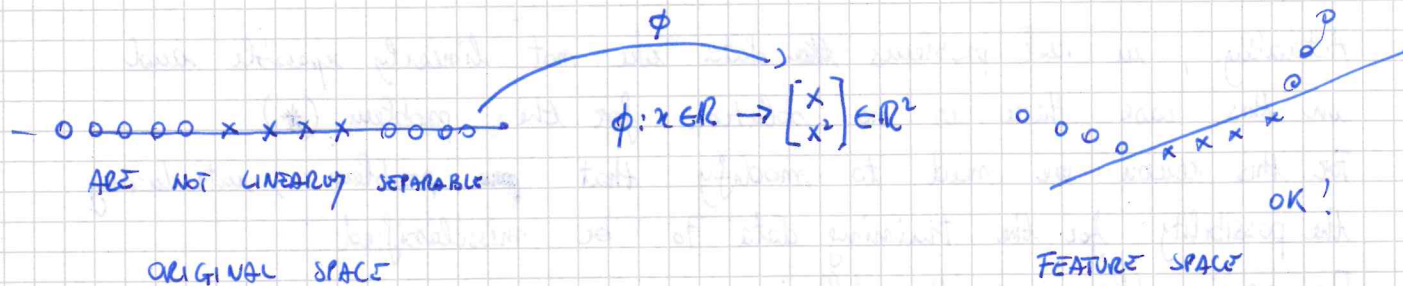
where  $Q_{ij} = y_i y_j x_i^T x_j$

once we obtain  $\alpha \Rightarrow w = \sum_{i=1}^N \alpha_i y_i x_i$

$$f(x) = \bar{w}^T x + \sigma = \sum_{i=1}^N \alpha_i y_i x_i^T x + \sigma$$

Vectors  $\bar{x}_i$  such that  $0 < \alpha_i < C$  are the support vectors

• NON LINEAR MODEL (NON LINEARLY SEPARABLE)



min  $w, \theta, \xi$

subject to

$$\frac{1}{2} \langle w, w \rangle + C \sum_{i=1}^N \xi_i$$

$$y_i (\langle w, \phi(x_i) \rangle + \theta) \geq 1 - \xi_i, \quad i = 1, \dots, N$$

$$\xi_i \geq 0$$

DUAL

min  $\alpha$

$$\frac{1}{2} \bar{\alpha}^T Q \bar{\alpha} - \bar{c}^T \bar{\alpha}$$

s.t.

$$\bar{y}^T \bar{\alpha} = \phi$$

$$0 < \alpha < C$$

$$w^* = \sum_{i=1}^N \bar{\alpha}_i^* y_i \phi(x_i)$$

where  $Q_{ij} = y_i y_j K_{ij}$

$$K_{ij} = K(x^i, x^j) := \langle \phi(x^i), \phi(x^j) \rangle$$

$K: \mathbb{R}^m \times \mathbb{R}^m \rightarrow \mathbb{R}$  is the kernel function

→ IN THE DUAL PROBLEM IT IS NOT NECESSARY TO KNOW EXACTLY THE FUNCTION  $\phi(\cdot)$  BUT WE CAN ONLY KNOW

$$K(\bar{x}, \hat{x}) = \langle \phi(\bar{x}), \phi(\hat{x}) \rangle = \phi(\bar{x})^T \phi(\hat{x})$$

$$h(x) = \text{sign}(f(x))$$

$$f(x) = \sum_{i=1}^N \alpha_i y_i \langle \phi(x_i), \phi(x) \rangle + \theta = \sum_{i=1}^N \alpha_i y_i K(x^i, x) + \theta$$