

Model Checking I

alias

Reactive Systems Verification

Luca Tesei

MSc in Computer Science, University of Camerino

Topics

- Channel Systems
- Synchronous and Asynchronous Communication
- SOS Semantics of Channel Systems as Transition Systems
- Examples

Material

Reading:

Chapter 2 of the book, pages 53–63.

More:

The slides in the following pages are taken from the material of the course “Introduction to Model Checking” held by Prof. Dr. Ir. Joost-Pieter Katoen at Aachen University.

Introduction

Modelling parallel systems

Transition systems

Modeling hard- and software systems

Parallelism and communication



Linear Time Properties

Regular Properties

Linear Temporal Logic

Computation-Tree Logic

Equivalences and Abstraction

representation of data-dependent parallel systems with

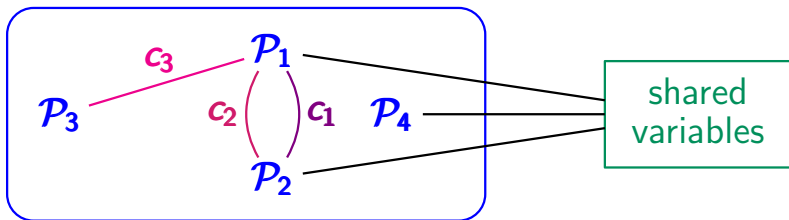
- communication over **shared variables**
- **synchronous** message passing
- **asynchronous** message passing

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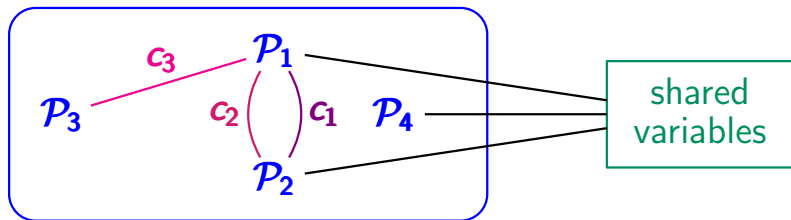
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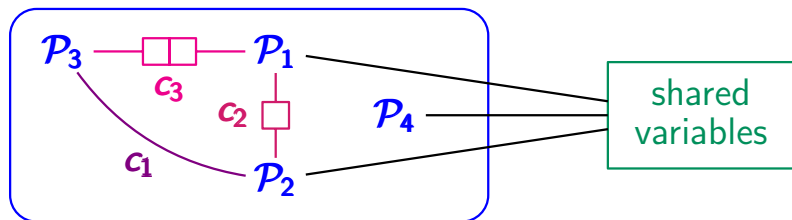
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channel types: **synchronous** or **FIFO**

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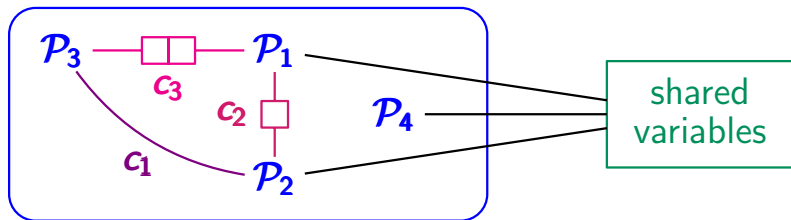


channel types: **synchronous** or **FIFO**

↑
capacity $\hat{=}$ number of buffer cells

representation of data-dependent parallel systems with

- communication over **shared variables**
- **synchronous** message passing ← **capacity 0**
- **asynchronous** message passing ← **capacity ≥ 1**



channel types: **synchronous** or **FIFO**

capacity **0**

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representation of data-dependent parallel systems with

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formalization through **program graphs** for $\mathcal{P}_1, \dots, \mathcal{P}_n$

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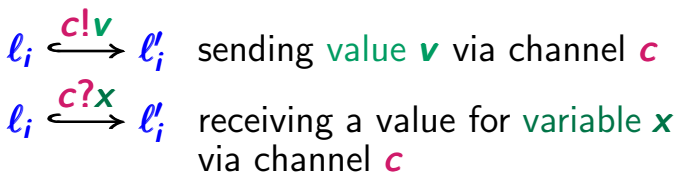
- with conditional transitions $l_i \xrightarrow{g:\alpha} l'_i$ (as before)

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- with conditional transitions $l_i \xrightarrow{g:\alpha} l'_i$ (as before)
- and **communication actions**



typed variable: variable x with data domain $Dom(x)$

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evaluation for a set Var of typed variables:

type-consistent function $\eta : Var \rightarrow Values$

↑
i.e., $\eta(x) \in Dom(x)$

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evaluation for a set $Chan$ of typed channels:

type-consistent function $\xi : Chan \rightarrow Values^*$

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evaluation for a set $Chan$ of typed channels:

type-consistent function $\xi : Chan \rightarrow Values^*$

s.t. $\xi(c)$ is a word over $Dom(c)$ of length $\leq cap(c)$

Channel system (CS)

PC2.2-25

$[P_1 | P_2 | \dots | P_n]$ where P_i are program graphs

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over a pair (Var , $Chan$)

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Var set of typed variables

$Chan$ set of typed channels with
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program graphs $P_i = (Loc_i, Act_i, Effect_i, \hookrightarrow_i, Loc_{0,i}, g_0)$
with conditional transitions

$l \xrightarrow{g:\alpha}_i l'$ guarded command

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$l \xrightarrow{g:\alpha}_i l'$ where $g \in Cond(Var)$, $\alpha \in Act_i$

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$l \xrightarrow{c!v}_i l'$ sending value v via channel c

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$l \xrightarrow{c?x}_i l'$ receiving a value for variable x via channel c

asynchronous message passing via channels of capacity ≥ 1

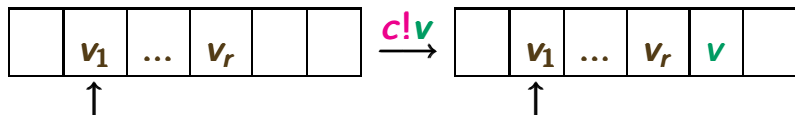
	enabled if ...	effect
sending $c!v$		
receiving $c?x$		

Effect of communication actions in CS

PC2.2-26

asynchronous message passing via channels of capacity ≥ 1

	enabled if ...	effect
sending $c!v$	channel c not full	$add(c, v)$
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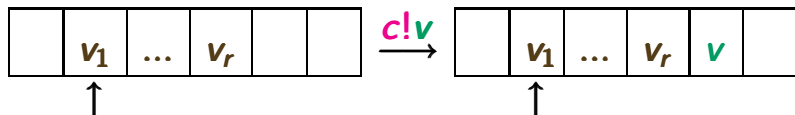


Effect of communication actions in CS

PC2.2-26

asynchronous message passing via channels of **capacity ≥ 1**

	enabled if ...	effect
sending $c!v$	channel c not full	$add(c, v)$
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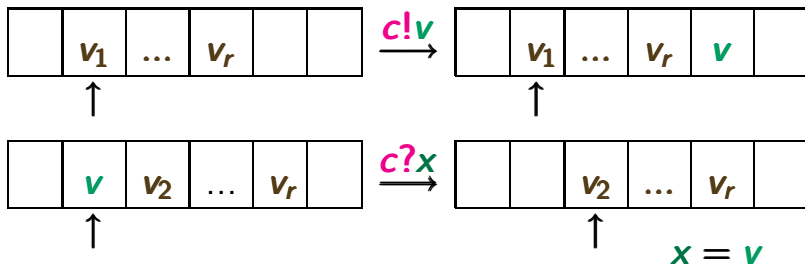


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synchronous message passing via channels of capacity 0

- $c!v$ and $c?x$ are executed at the same time
- effect $x := v$

channel system over (*Var*, *Chan*)

$$\mathcal{C} = [\mathcal{P}_1 | \dots | \mathcal{P}_n]$$



transition system $\mathcal{T}_{\mathcal{C}}$

channel system over (Var , Chan)
 $\mathcal{C} = [\mathcal{P}_1 \mid \dots \mid \mathcal{P}_n]$



transition system $\mathcal{T}_{\mathcal{C}}$

states of $\mathcal{T}_{\mathcal{C}}$ have the form

$\langle l_1, \dots, l_n, \eta, \xi \rangle$
locations of $\mathcal{P}_1, \dots, \mathcal{P}_n$ variable valuation channel evaluation

states $\langle l_1, \dots, l_n, \eta, \xi \rangle$ where

l_i location of program graph \mathcal{P}_i ,

$\eta \in \mathit{Eval}(\mathit{Var})$ variable evaluation

$\xi \in \mathit{Eval}(\mathit{Chan})$ channel evaluation

states $\langle \ell_1, \dots, \ell_n, \eta, \xi \rangle$ where

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variable evaluation:

$$\eta : \mathit{Var} \longrightarrow \bigcup_{x \in \mathit{Var}} \mathit{Dom}(x) \quad \text{with } \eta(x) \in \mathit{Dom}(x)$$

channel evaluation:

$$\xi : \mathit{Chan} \longrightarrow \bigcup_{c \in \mathit{Chan}} \mathit{Dom}(c)^* \quad \text{with } \xi(c) \in \mathit{Dom}(c)^* \\ \text{and } |\xi(c)| \leq \mathit{cap}(c)$$

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and $|\xi(c)| \leq \mathit{cap}(c)$



only channels c with $\mathit{cap}(c) \geq 1$ are relevant

states $\langle l_1, \dots, l_n, \eta, \xi \rangle$ where $l_i \in \text{Loc}_i$, $\eta \in \text{Eval}(\text{Var})$,
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transition relation \longrightarrow is given by SOS-rules:

- interleaving rules for $\alpha \in \mathbf{Act}_i$
- rules for message passing along channels

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interleaving rule for actions $\alpha \in \mathbf{Act}_i$:

$$\frac{l_i \xrightarrow{g:\alpha}_i l'_i \wedge \eta \models g}{\langle l_1, \dots, l_i, \dots, l_n, \eta, \xi \rangle \xrightarrow{\alpha} \langle l_1, \dots, l'_i, \dots, l_n, \mathbf{Effect}_i(\alpha, \eta), \xi \rangle}$$

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↑

does not affect the channel evaluation ξ

for channel c with $cap(c) \geq 1$

SOS-rules for asynchronous message passing

for channel c with $cap(c) \geq 1$

receiving a message:

$$\frac{l_i \xrightarrow{c?x} l'_i \wedge \xi(c) = v_1 v_2 \dots v_k \wedge k \geq 1}{\langle l_1, \dots, l_i, \dots, l_n, \eta, \xi \rangle \xrightarrow{T} \langle l_1, \dots, l'_i, \dots, l_n, \eta', \xi' \rangle}$$

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where $\eta' = \eta[x := v_1]$

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SOS-rules for asynchronous message passing

for channel c with $cap(c) \geq 1$

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sending a message:

$$\frac{l_i \xrightarrow{c!v}_i l'_i \wedge \xi(c) = v_1 \dots v_k \wedge k < cap(c)}{\langle l_1, \dots, l_i, \dots, l_n, \eta, \xi \rangle \xrightarrow{T} \langle l_1, \dots, l'_i, \dots, l_n, \eta, \xi[c := v_1 \dots v_k v] \rangle}$$

for synchronous channel c :

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where $\eta' = \eta[x:=v]$ and $\xi' = \xi$

has a transition system for a channel system with ... ?

- 2 processes with 2 locations each
- 2 Boolean variables
- 2 channels of capacity 10 and Boolean values

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answer:

$$2 * 2 * 2 * 2 * (2^{11} - 1) * (2^{11} - 1)$$

$$\text{note: } 2^{11} - 1 = 1 + 2 + 2^2 + \dots + 2^{10}$$

How many states...

PC2.2-31

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$$2 * 2 * 2 * 2 * (2^{11} - 1) * (2^{11} - 1) > 2^{24} > 25 \text{ mio}$$

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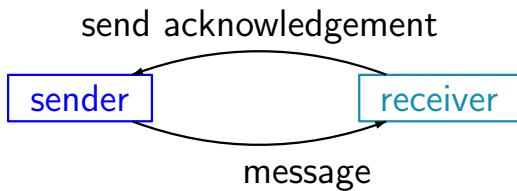
answer:

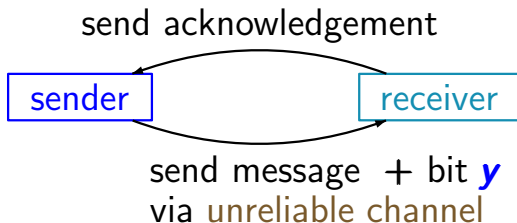
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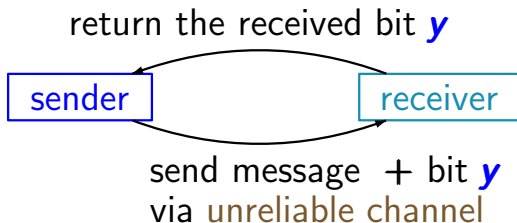
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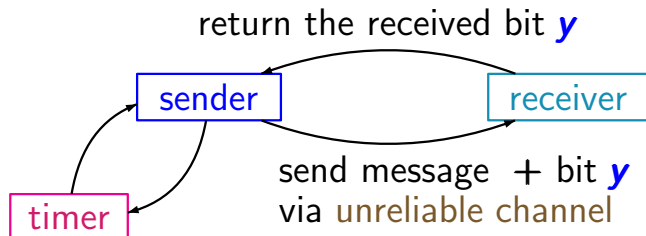
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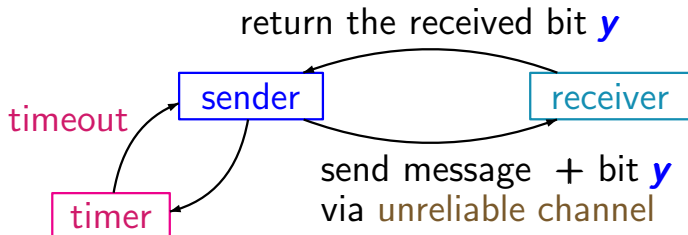
answer: ∞











LOOP FOREVER

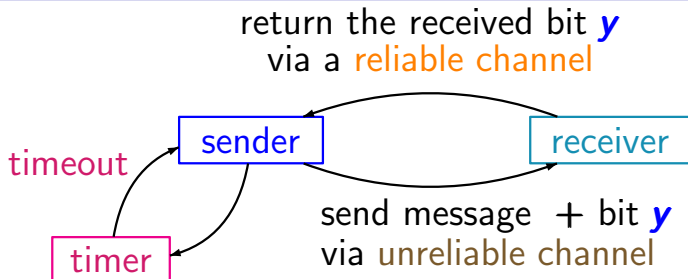
(1) send message + **bit y** and activate timer

(2) AWAIT **timeout** or **acknowledgement** DO

 IF **timeout** THEN goto (1)

 ELSE turn off timer; **$y := \neg y$**

OD
FI



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If both channels are unreliable ...

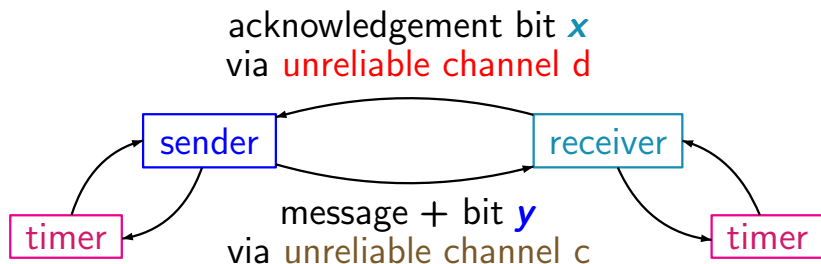
PC2.2-33

acknowledgement bit x
via **unreliable channel d**



If both channels are unreliable ...

PC2.2-33

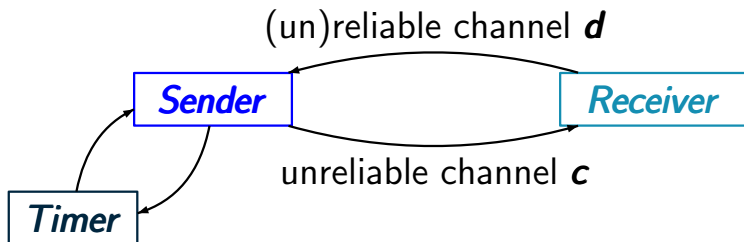


LOOP FOREVER

- (1) send message + bit y and activate timer
- (2) AWAIT **timeout** or **acknowledgement x** DO
 IF **timeout** THEN goto (1)
 ELSE IF $x=y$ THEN turn off timer; $y:=\neg y$
 ELSE ignore x
 FI
OD

Alternating bit protocol (ABP)

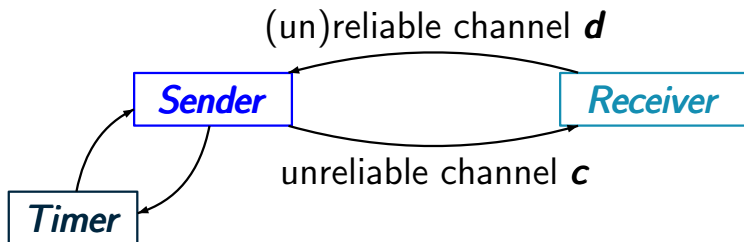
PC2.2-34



channel system: [**Sender** | **Timer** | **Receiver**]

Alternating bit protocol (ABP)

PC2.2-34



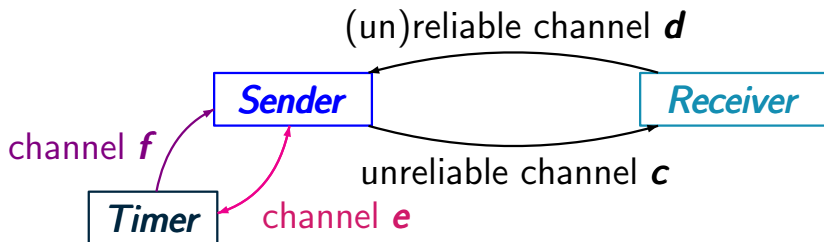
channel system: [*Sender* | *Timer* | *Receiver*]

synchronous message passing between
Timer and *Sender*

asynchronous message passing between
Receiver and *Sender*

Alternating bit protocol (ABP)

PC2.2-34



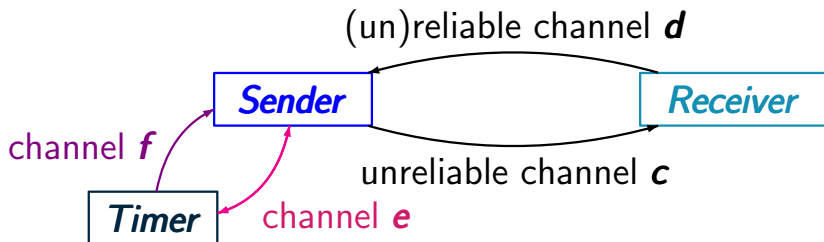
channel system: [**Sender** | **Timer** | **Receiver**]

synchronous message passing between
Timer and **Sender** ← channels **e** and **f**

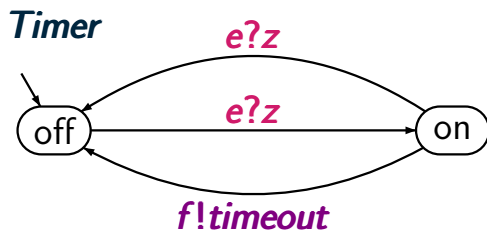
asynchronous message passing between
Receiver and **Sender** ← channels **c** , **d**

Alternating bit protocol (ABP)

PC2.2-34

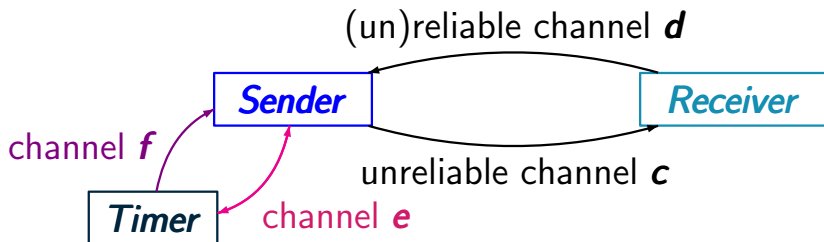


channel system: [**Sender** | **Timer** | **Receiver**]

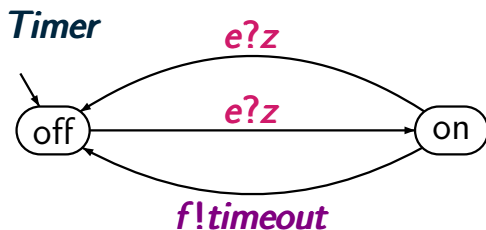


Alternating bit protocol (ABP)

PC2.2-34

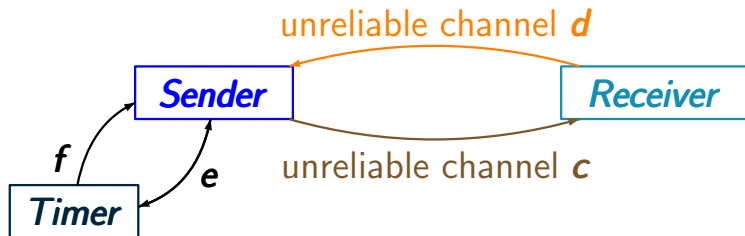


channel system: $[\textit{Sender} \mid \textit{Timer} \mid \textit{Receiver}]$



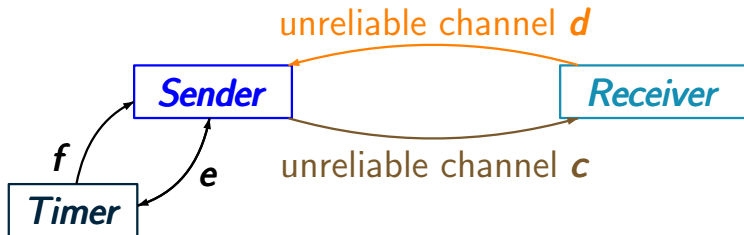
actions of ***Sender***:

\vdots
 $e!timer_on$
 $e!timer_off$
 $f?z'$
 \vdots



specify the **sender** by a program graph using

- asynchronous channels **c** and **d**
- synchronous channels **e** and **f**

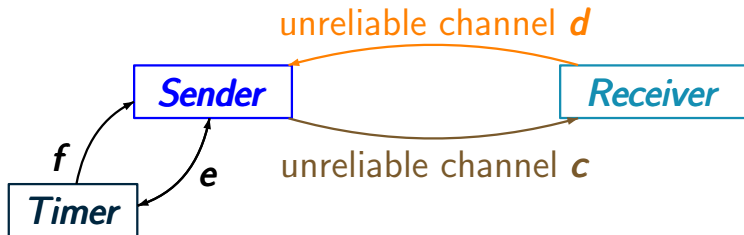


specify the **sender** by a program graph using

- asynchronous channels **c** and **d**
- synchronous channels **e** and **f**

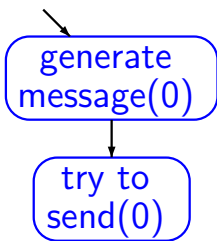
simply write

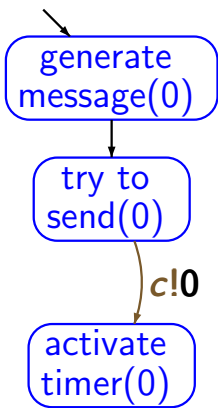
!timeout
?timer_on
?timer_off

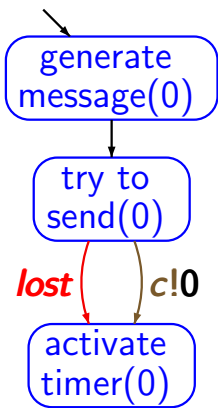


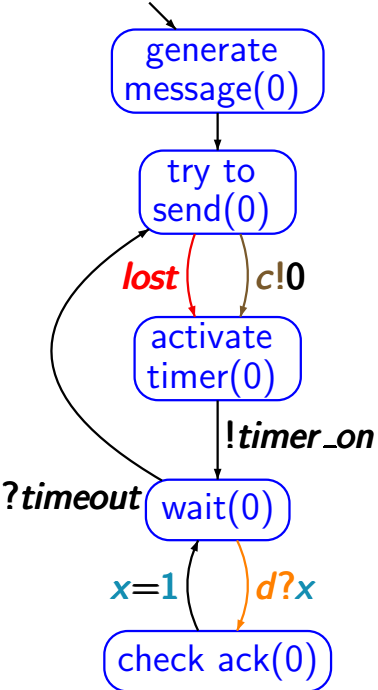
specify the **sender** by a program graph using

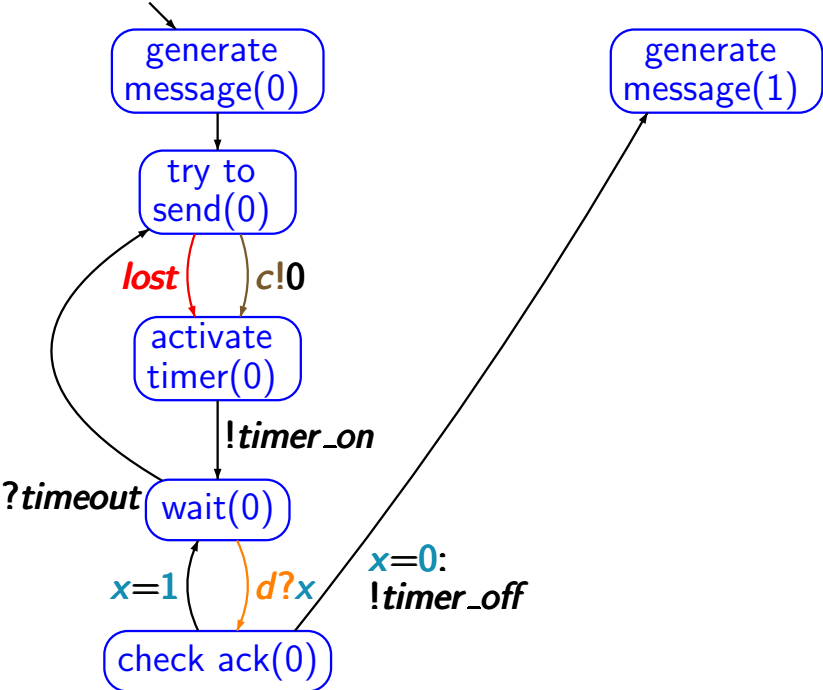
- asynchronous channels ***c*** and ***d***
- synchronous channels ***e*** and ***f***
- Boolean variable ***x*** for the acknowledgement bit sent by the receiver

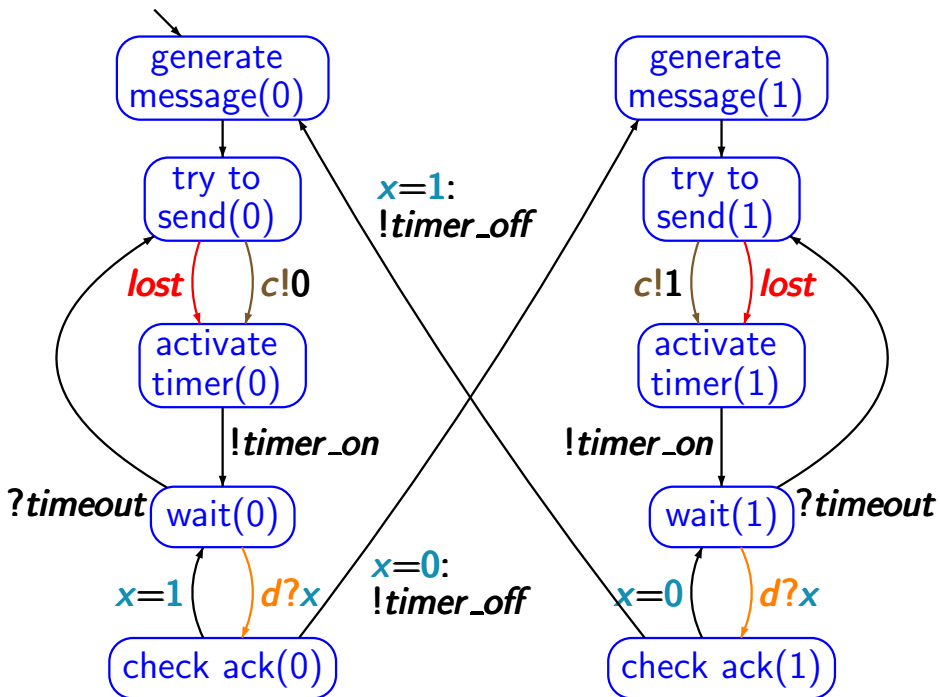






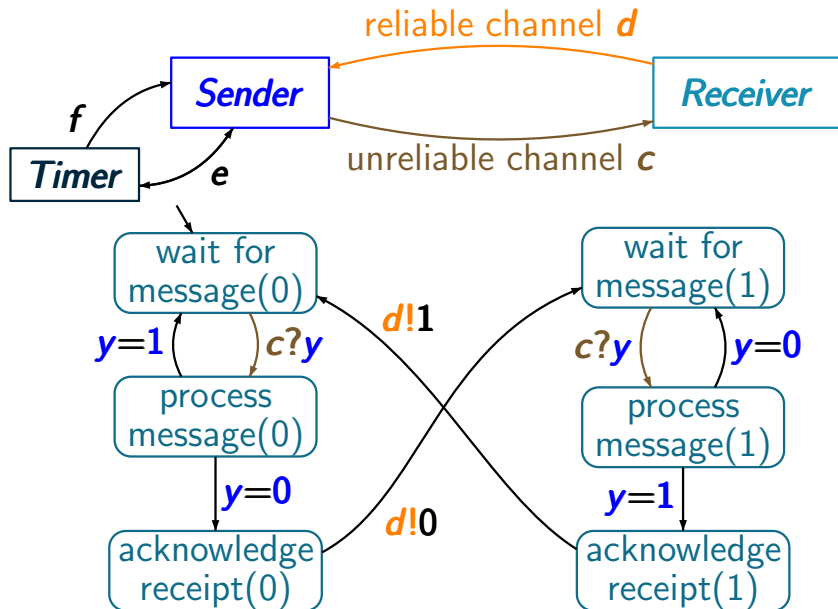


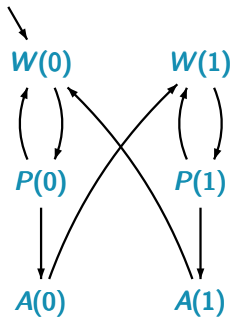
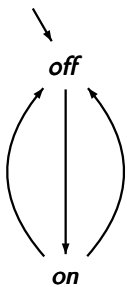
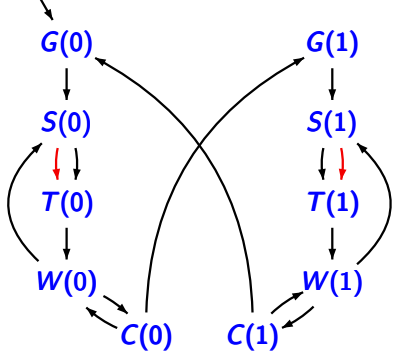


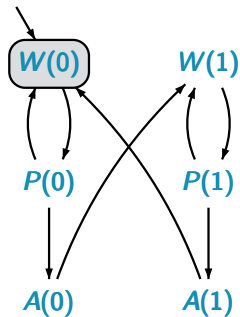
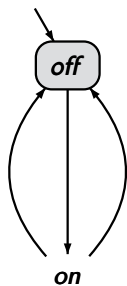
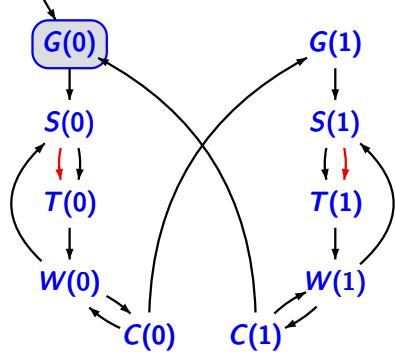


Program graph for the receiver

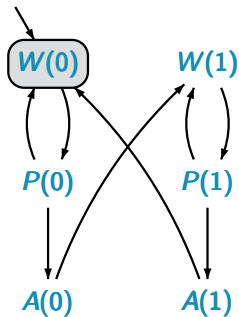
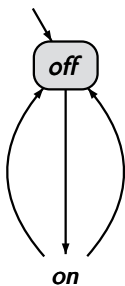
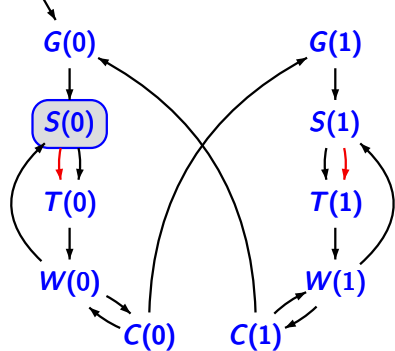
PC2.2-36







Generate(0) off Wait(0) $c = \epsilon$ $d = \epsilon$



Generate(0)

off

Wait(0)

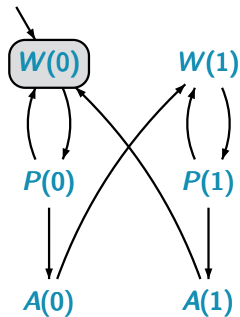
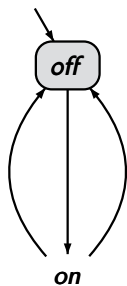
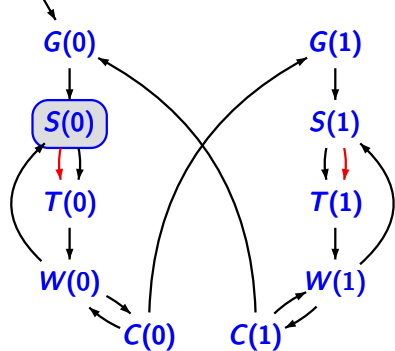
$c = \epsilon$ $d = \epsilon$

Send(0)

off

Wait(0)

$c = \epsilon$ $d = \epsilon$



Generate(0)

off

Wait(0)

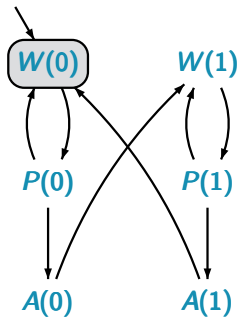
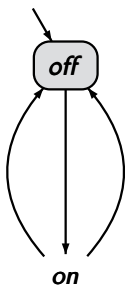
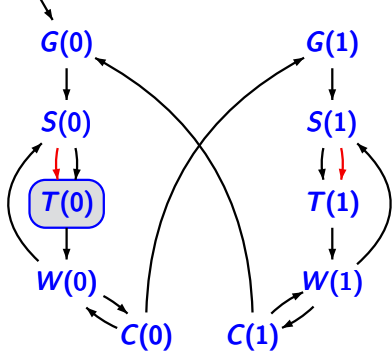
$c = \epsilon$ $d = \epsilon$

Send(0)

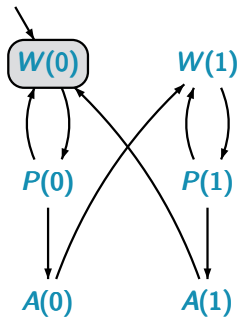
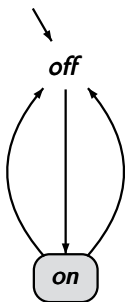
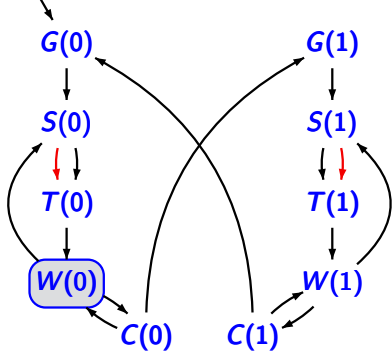
off

Wait(0)

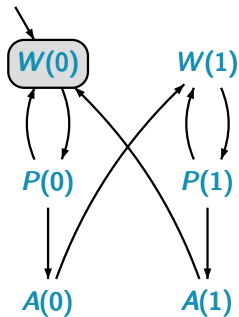
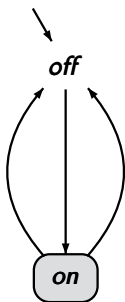
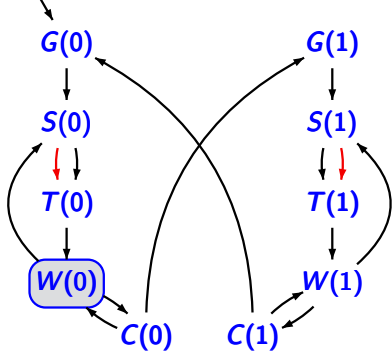
$c = \epsilon$ $d = \epsilon$ message **lost**



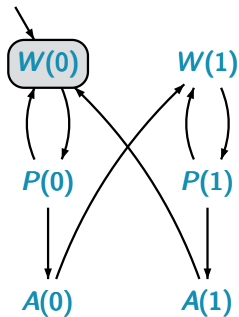
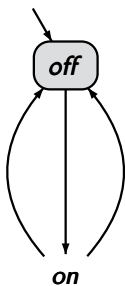
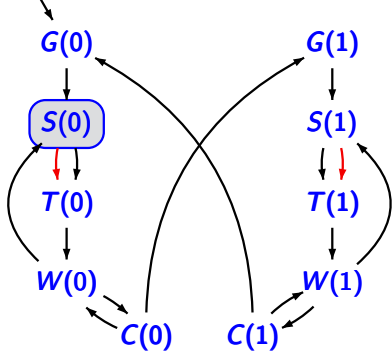
Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message lost
Timer_on(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	



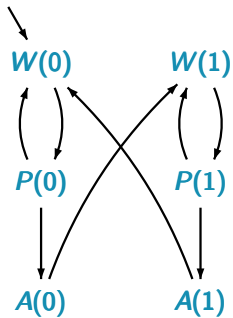
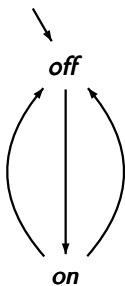
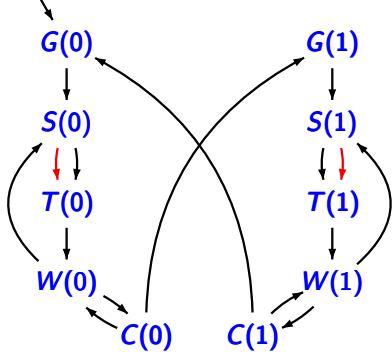
Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message lost
Timer_on(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = \epsilon$	$d = \epsilon$	

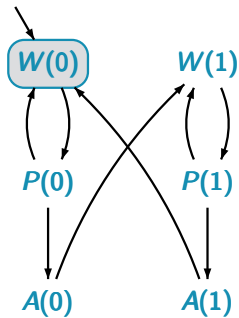
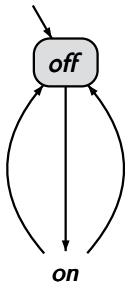
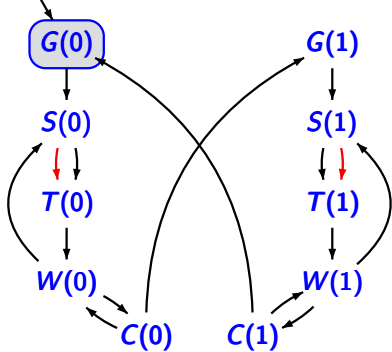


Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message lost
Timer_on(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = \epsilon$	$d = \epsilon$	timeout

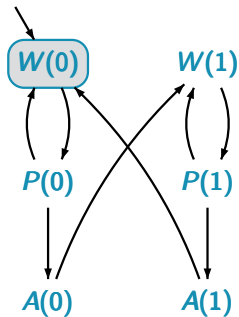
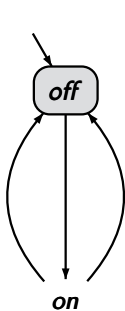
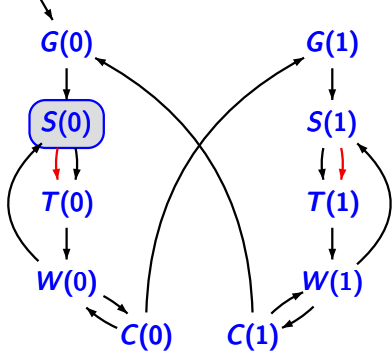


Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message lost
Timer_on(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = \epsilon$	$d = \epsilon$	timeout
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
	:				try again





Generate(0) off Wait(0) $c=\epsilon$ $d=\epsilon$



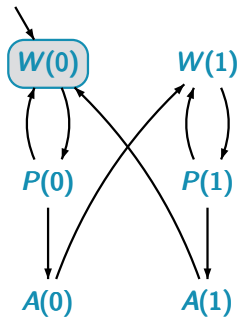
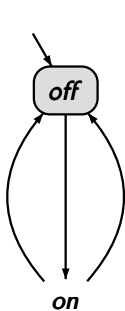
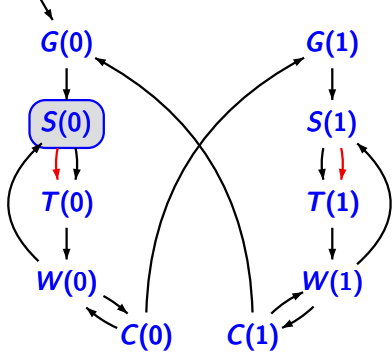
Generate(0)
Send(0)

off
off

Wait(0)
Wait(0)

$c = \epsilon$
 $c = \epsilon$

$d = \epsilon$
 $d = \epsilon$



Generate(0)
Send(0)

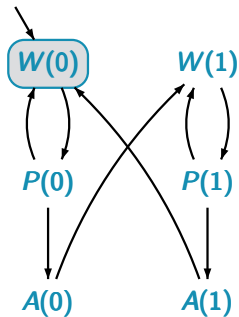
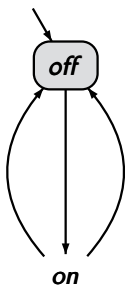
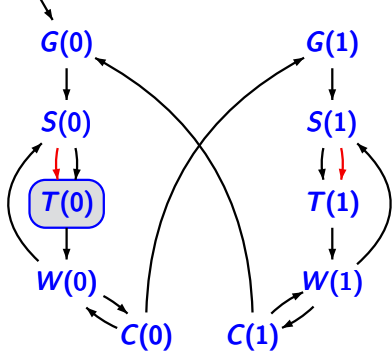
off
off

Wait(0)
Wait(0)

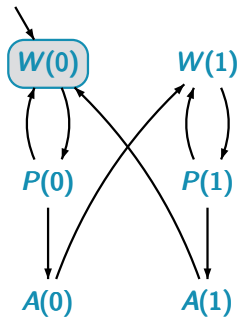
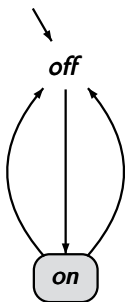
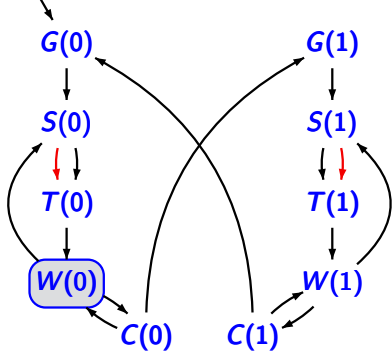
$c = \epsilon$
 $c = \epsilon$

$d = \epsilon$
 $d = \epsilon$

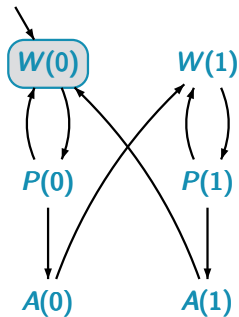
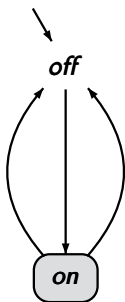
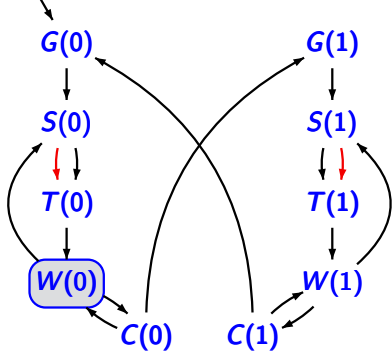
message 0 sent



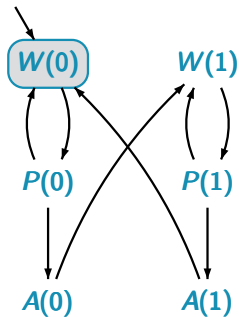
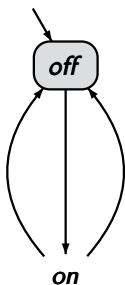
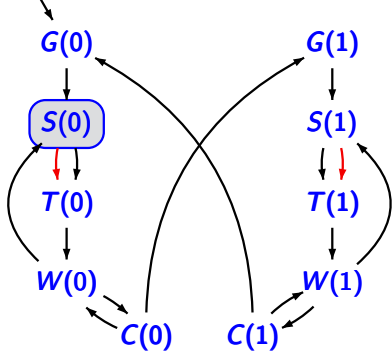
Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message 0 sent
Timer_on(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	



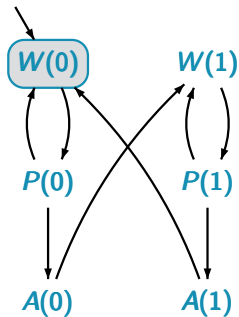
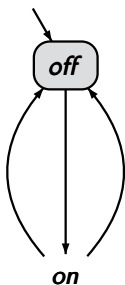
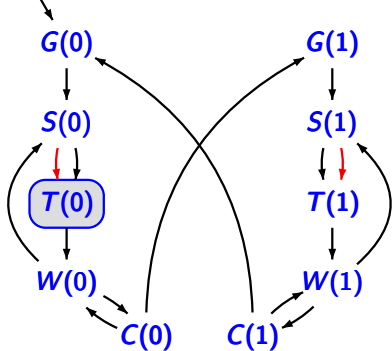
Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message 0 sent
Timer_on(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = 0$	$d = \epsilon$	



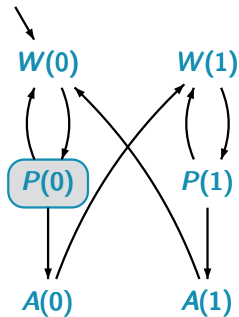
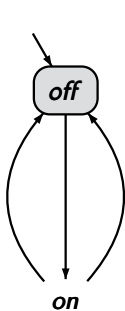
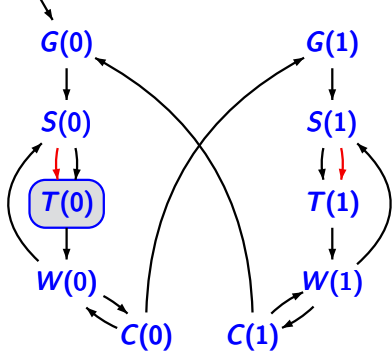
Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message 0 sent
Timer_on(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = 0$	$d = \epsilon$	timeout



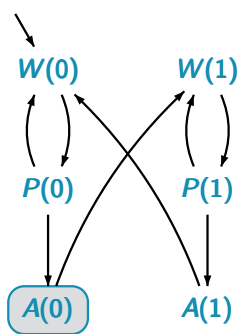
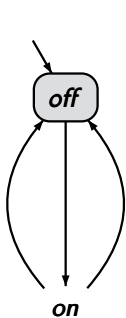
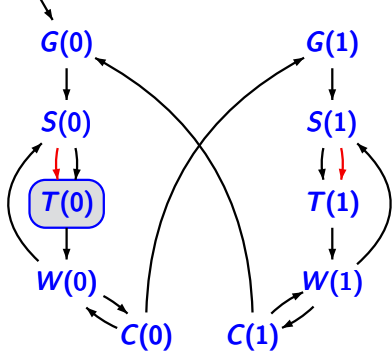
Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message 0 sent
Timer_on(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = 0$	$d = \epsilon$	timeout
Send(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	



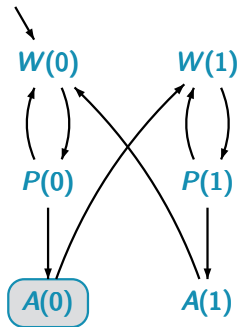
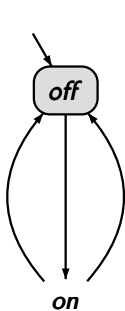
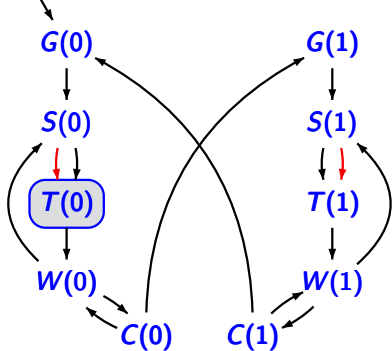
Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message 0 sent
Timer_on(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = 0$	$d = \epsilon$	timeout
Send(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	0 sent again
Timer_on(0)	off	Wait(0)	$c = 00$	$d = \epsilon$	



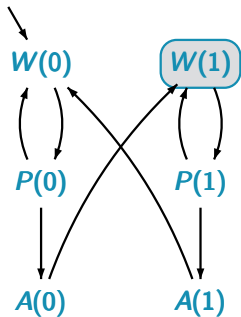
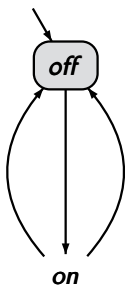
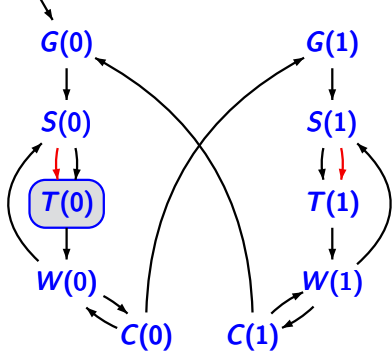
Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message 0 sent
Timer_on(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = 0$	$d = \epsilon$	timeout
Send(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	0 sent again
Timer_on(0)	off	Wait(0)	$c = 00$	$d = \epsilon$	
Timer_on(0)	off	Proc(0)	$c = 0$	$d = \epsilon$	message received



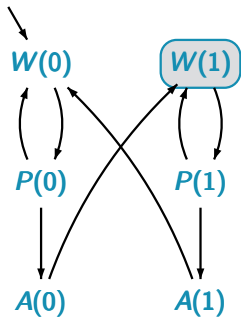
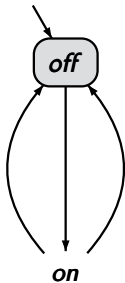
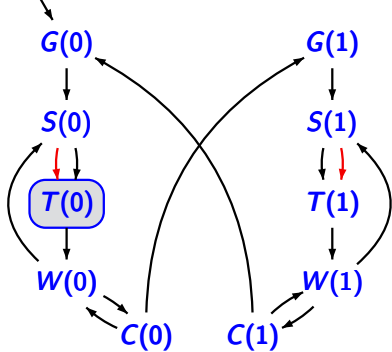
Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message 0 sent
Timer_on(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = 0$	$d = \epsilon$	timeout
Send(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	0 sent again
Timer_on(0)	off	Wait(0)	$c = 00$	$d = \epsilon$	
Timer_on(0)	off	Proc(0)	$c = 0$	$d = \epsilon$	message received
Timer_on(0)	off	Ack(0)	$c = 0$	$d = \epsilon$	



Generate(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	
Send(0)	off	Wait(0)	$c = \epsilon$	$d = \epsilon$	message 0 sent
Timer_on(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	
Wait(0)	on	Wait(0)	$c = 0$	$d = \epsilon$	timeout
Send(0)	off	Wait(0)	$c = 0$	$d = \epsilon$	0 sent again
Timer_on(0)	off	Wait(0)	$c = 00$	$d = \epsilon$	
Timer_on(0)	off	Proc(0)	$c = 0$	$d = \epsilon$	message received
Timer_on(0)	off	Ack(0)	$c = 0$	$d = \epsilon$	send ack via d



⋮	⋮	⋮	⋮	⋮	
Wait(0)	on	Wait(0)	$c=0$	$d=\epsilon$	timeout
Send(0)	off	Wait(0)	$c=0$	$d=\epsilon$	0 sent again
Timer_on(0)	off	Wait(0)	$c=00$	$d=\epsilon$	
Timer_on(0)	off	Proc(0)	$c=0$	$d=\epsilon$	message received
Timer_on(0)	off	Ack(0)	$c=0$	$d=\epsilon$	send ack via d
Timer_on(0)	off	Wait(1)	$c=0$	$d=0$	receiver changes its mode



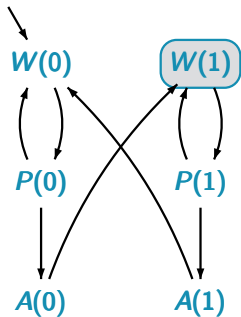
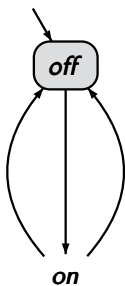
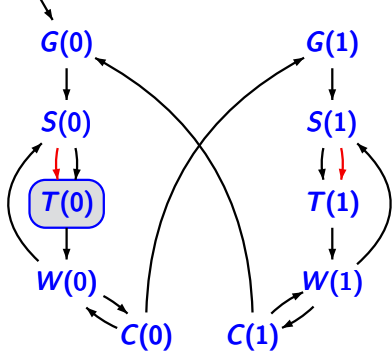
⋮
Timer_on(0)

⋮
off

⋮
Wait(1)

⋮
 $c=0$

⋮
 $d=0$



⋮
Timer_on(0)

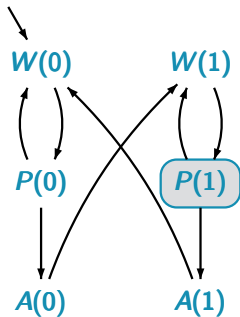
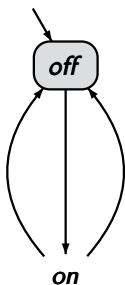
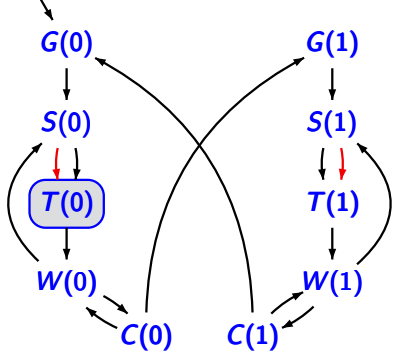
⋮
off

⋮
Wait(1)

⋮
 $c=0$

⋮
 $d=0$

receiver reads the
same message again



⋮
Timer_on(0)

⋮
off

⋮
Wait(1)

⋮
 $c=0$

⋮
 $d=0$

receiver reads the
same message again

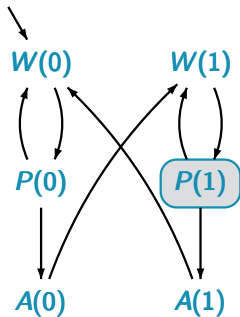
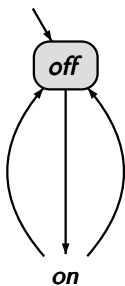
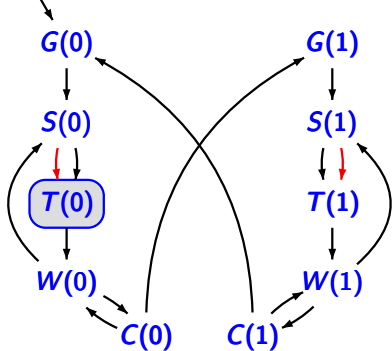
Timer_on(0)

off

Proc(1)

$c=\epsilon$

$d=0$



⋮
Timer_on(0)

⋮
off

⋮
Wait(1)

⋮
 $c=0$

⋮
 $d=0$

receiver reads the
same message again

Timer_on(0)

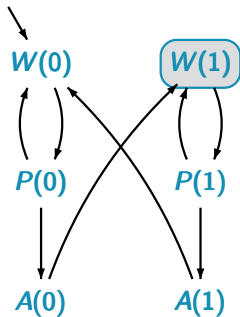
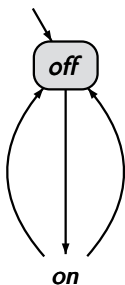
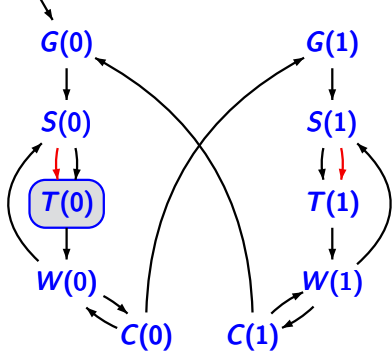
off

Proc(1)

$c=\epsilon$

$d=0$

receiver discards
the message



⋮
Timer_on(0)

⋮
off

⋮
Wait(1)

⋮
 $c=0$

⋮
 $d=0$

receiver reads the same message again

Timer_on(0)

off

Proc(1)

$c=\epsilon$

$d=0$

receiver discards the message

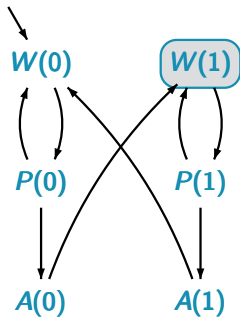
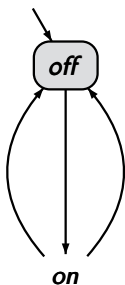
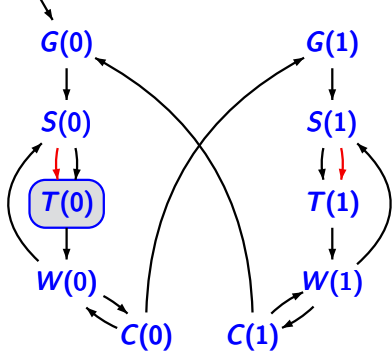
Timer_on(0)

off

Wait(1)

$c=\epsilon$

$d=0$

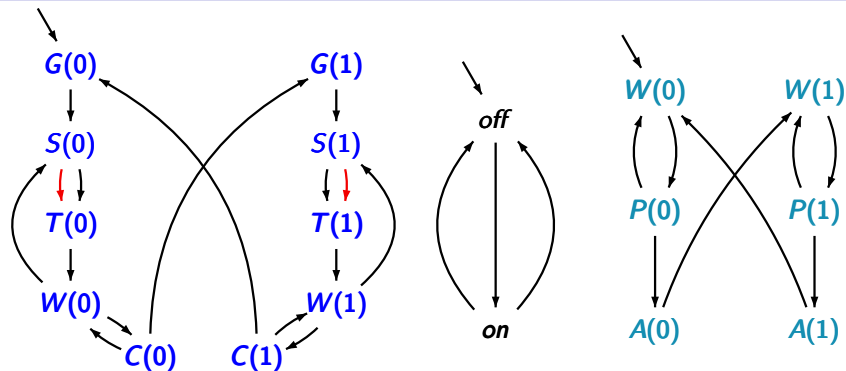


⋮	⋮	⋮	⋮	⋮	
Timer_on(0)	off	Wait(1)	$c=0$	$d=0$	
Timer_on(0)	off	Proc(1)	$c=\epsilon$	$d=0$	
Timer_on(0)	off	Wait(1)	$c=\epsilon$	$d=0$	
⋮	⋮	⋮	⋮	⋮	

receiver reads the same message again
 receiver discards the message

Alternating bit protocol (ABP)

PC2.2-37C

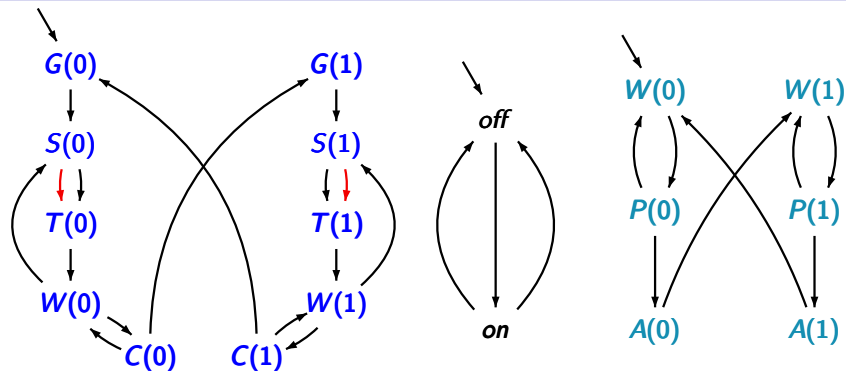


number of states in the TS:

$$10 \cdot 2 \cdot 6 \cdot \# \text{channel evaluations}$$

Alternating bit protocol (ABP)

PC2.2-37C



number of states in the TS:

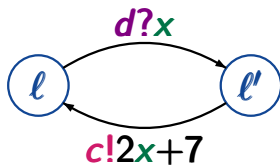
$10 \cdot 2 \cdot 6 \cdot \# \text{channel evaluations}$

$> 10^8$ for FIFOs with capacity 10

- conditional communication actions $l \xleftrightarrow{g:c?x} l'$

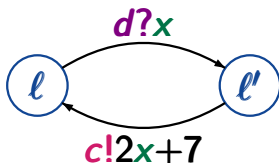
- conditional communication actions $l \xrightarrow{g:c?x} l'$
- generalized sending instructions $c!expr$ instead of $c!v$

e.g.



- conditional communication actions $l \xleftrightarrow{g:c?x} l'$
- generalized sending instructions $c!expr$ instead of $c!v$

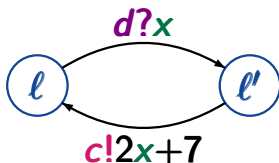
e.g.



- communication as conditions $l \xleftrightarrow{c?x:\alpha} l'$

- conditional communication actions $l \xleftrightarrow{g:c?x} l'$
- generalized sending instructions $c!expr$ instead of $c!v$

e.g.



- communication as conditions $l \xleftrightarrow{c?x:\alpha} l'$

\rightsquigarrow more compact TS-representations

- conditional communication actions $l \xleftrightarrow{g:c?x} l'$
- generalized sending instructions $c!expr$ instead of $c!v$
- communication as conditions $l \xleftrightarrow{c?x:\alpha} l'$
- *open* channel systems $\mathcal{P}_1 | \dots | \mathcal{P}_n$
instead of *closed* channel systems $[\mathcal{P}_1 | \dots | \mathcal{P}_n]$

Variants of channel systems

pc2.2-38

- conditional communication actions $l \xleftrightarrow{g:c?x} l'$
- generalized sending instructions $c!expr$ instead of $c!v$
- communication as conditions $l \xleftrightarrow{c?x:\alpha} l'$
- *open* channel systems $\mathcal{P}_1 | \dots | \mathcal{P}_n$
instead of *closed* channel systems $[\mathcal{P}_1 | \dots | \mathcal{P}_n]$

