Exercise 5

Consider a language of concatenated instructions. Instructions can be blocks or other kind of instructions. A block consists of a declaration of variables, which can be of type integer or real, followed by a sequence of instructions.

Define a Syntax Directed Translation Scheme suitable for being implemented during topdown parsing that computes, for each instruction, an attribute *depth* and an attribute *occupation*. The depth is the number of blocks in which the instruction is enclosed and the occupation, for a block, is the maximum number of bytes needed to store all the variables declared in the block and in its sub-blocks. The space used for a sub-block S can be reused by another sub-block S' when the block S is closed. Integer variables occupy two bytes, real variables occupy four bytes and other kind of instructions occupies zero bytes.

For example, in the following case:

```
begin
  var a,b,c: integer;
  S;
  begin
   var d: real;
   S'
  end;
  begin
   var e: integer;
   S'';
   S'''
  end;
end;
end;
```

supposing that instructions S, S', S" and S"' are not blocks, the expected value of the attributes are: external block: depth = 0, occupation = 10; instruction S: depth = 1, occupation = 0; first internal block: 1, 4; instruction S': 2, 0; second internal block: 1, 2; S" and S"': 2, 0.

The use of global data structures is forbidden.

Hints

Proceeds in the following order:

- 1. Define an LL(1) grammar and check its correctness
- 2. The requested analyses can be conducted independently from each others:

- a. Define two synthesised attributes for the computation of the memory occupation
- b. Define one synthesised attribute and one inherited attribute to compute the number of sub-block nesting

Solution

Let's use the following grammar (verify that it is LL(1)):

```
Program::= Block

B::= begin Declaration ; Command Rest_of_program end

R::= ; C R

R::= \epsilon

C::= Block

C::= Statement

D::= var id List_of_identifiers : Type

L ::= , id L

L::= \epsilon

T ::= real

T ::= int
```

The following attributes are used:

- **M** for B, D, R, C, T is a synthesized attribute containing a number of bytes
 - in case of B: the bytes required for the declaration and the maximum number of bytes for the blocks occurring in the body of B
 - \circ in case of D: the bytes required for the variables in D
 - o in case of R, C: bytes required by the associated blocks or statements
 - in case of T: bytes for one integer or one real
- **n** for L is a synthesised attribute containing the number of variables for computing the level of scoping (depth)
- in for B, C, R is an inherited attribute containing the level at which the associated structure is nested
- **H** for B, C is a synthesised attribute containing the depth of the associated structure

```
P::= {B.in:=0}

B

B::= begin

D; {C.in:= B.in +1}

C {R.in:= B.in +1}

R end {B.M:= D.M + max(C.M, R.M); B.H:=

B.in +1}
```

$R_{1}::=; \{C.in:=R_{1}.in\} \\C \{R_{2}.in:=R_{1}.in\} \\R_{2} \{R_{1}.M:=max(C.M, R_{2}.M)\}$
$\mathbf{R} ::= \varepsilon \{ \mathbf{R} \cdot \mathbf{M} := 0 \}$
C::= {B.in:= C.in} B {C.M:= B.M; C.H:= C.in}
C::= S {C.M:=0; C.H:=C.in}
D::= var id L : T {D.M:= (1+L.n) * T.M}
$L_{1} ::= , id L_{2} \{L_{1} ::= 1 + L_{2} :n \}$
$L::= \varepsilon \{L.n:=0\}$
T ::= real $\{T.M:=4\}$
$T ::= int \{T.M:=2\}$