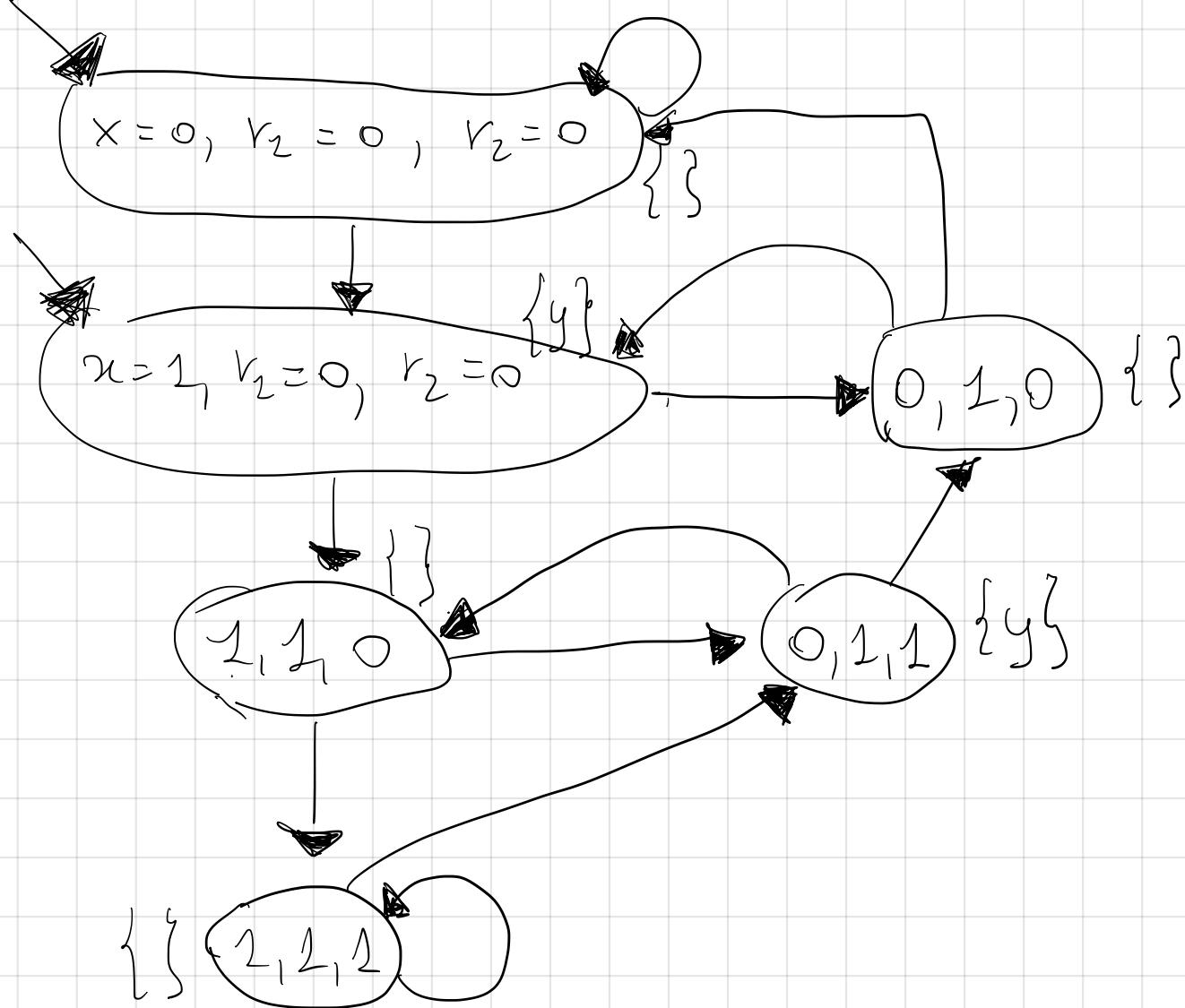


$$\underline{\text{Ex1}} \quad \delta_{r_2} = r_2 \vee x \quad \delta_{r_2} = r_2 \wedge x$$

$$y = (r_2 \vee x) \text{ XOR } (r_2 \wedge x)$$



$$\underline{\text{Ex2}} \quad \text{a) } E_2 = \left\{ A_0, A_1, \dots \in (2^{\text{AP}})^\omega \mid \right.$$

$(\forall i \in \mathbb{N} : A_i \in A_i \Rightarrow (\exists j \in \mathbb{N} : j > i \wedge B \in A_j)) \wedge$

$(\forall k \in \mathbb{N} . B \in A_k \Rightarrow C \in A_k) \}$

In LTL: $\Box(A \rightarrow \Diamond B) \wedge \Box(B \rightarrow C)$

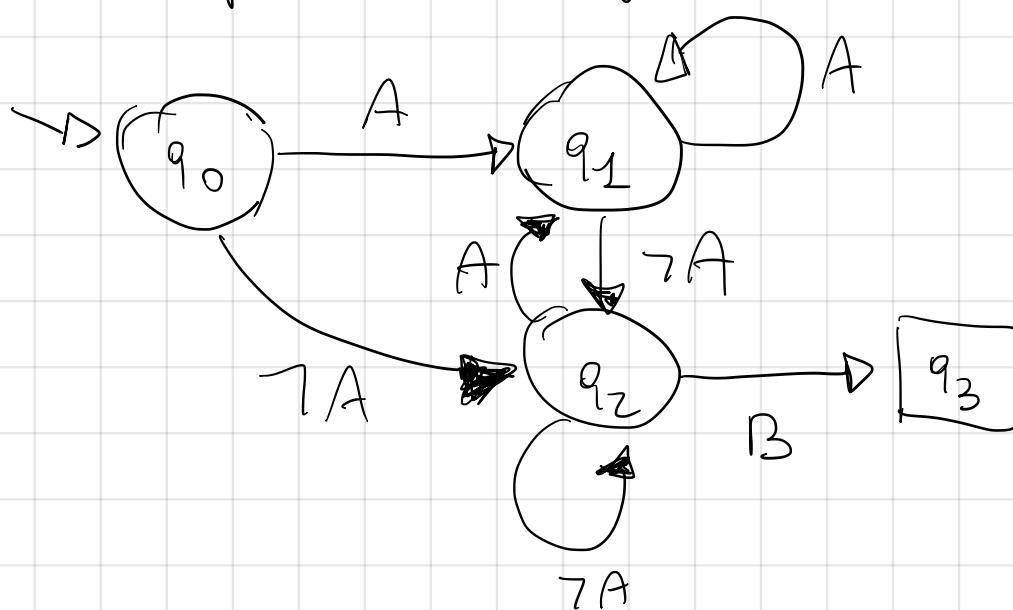
This is a mixed property.

b) $E_b = \{A_0 A_1 \dots \in (2^{AP})^\omega \mid \forall i \in \mathbb{N}, i > 0 \Rightarrow (A \in A_i \Rightarrow B \in A_{i-1})\}$

In LTL: $\Box(\Diamond A \rightarrow B)$

This is an invariant, so a safety property.

An NFA recognising the language of Minimal Bad Prefixes is as follows:



The state q_1 records the information " A was seen in the previous step". The state q_2 records the information " A was not seen in the previous step".

$$c) E_C = \left\{ A_0 A_1 \dots \in (2^{\text{AP}})^\omega \mid \forall i \in \mathbb{N}. \quad B \in A_i \Rightarrow \right. \\ \left. (\exists k \in \mathbb{N}: k > i \wedge (B \in A_k)) \right\}$$

In LTL : $\square(B \rightarrow \square C)$

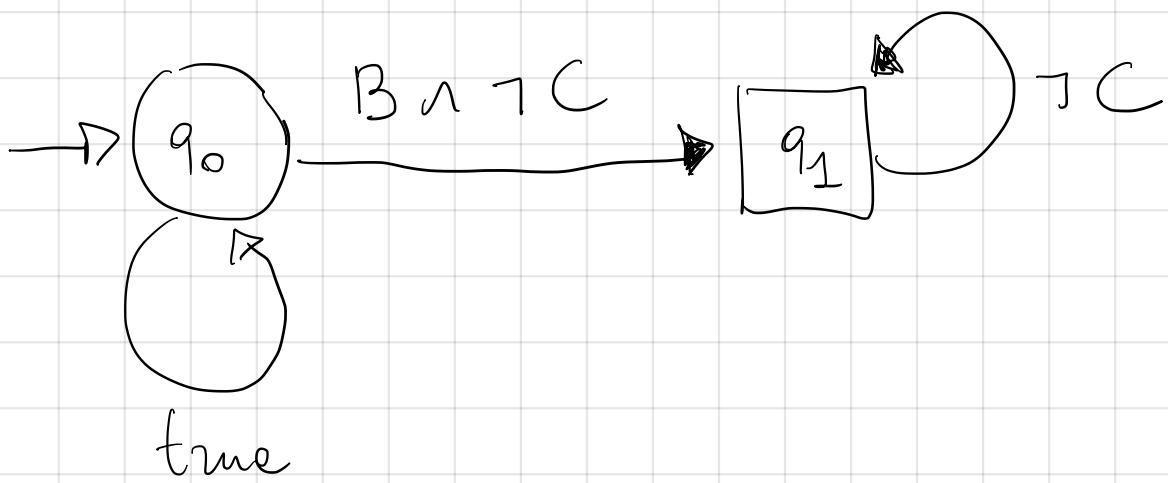
This is a pure liveness property.

Bad Behaviors are those satisfying

$$\begin{aligned} \neg \square(B \rightarrow \square C) &\equiv \square \neg(B \rightarrow \square C) \\ &\equiv \square \neg(\neg B \vee \square C) \equiv \square(\neg \neg B \wedge \neg \square C) \\ &\equiv \square(B \wedge \square \neg C) \end{aligned}$$

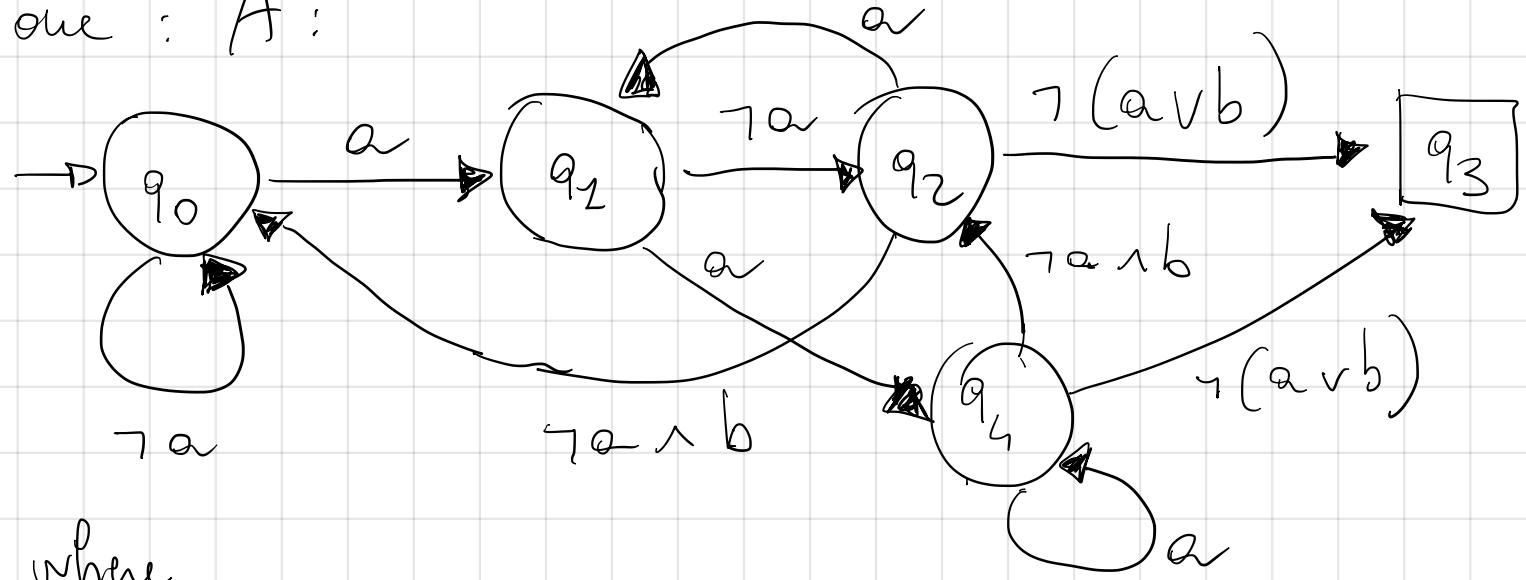
An NBA accepting the words that satisfy

$\square(B \wedge \square \neg C)$ is as follows :



Ex3 An NFA (non-blocking) for the minimal bad prefixes of φ is the following

one : A :



where

$$\gamma_a = \{\{\}, \{b\}, \{c\}, \{b, c\}\}$$

$$a = \{\{a\}, \{a, b\}, \{a, c\}, \{a, b, c\}\}$$

$$\gamma(a \vee b) = \{\{\}, \{c\}\}$$

$$\gamma a \wedge b = \{\{b\}, \{b, c\}\}$$

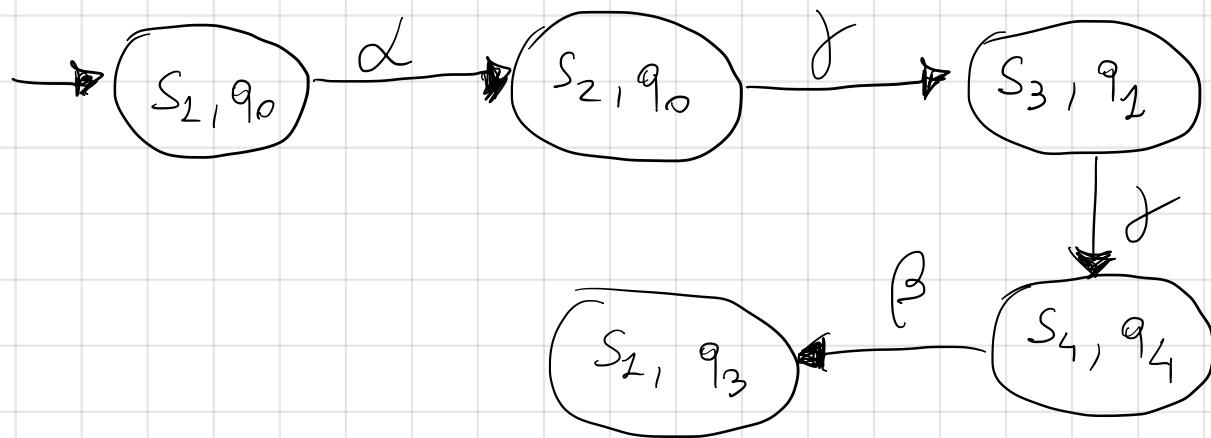
Let us construct the product $\overline{TS} \otimes A$

The initial states are given by

$$\delta(q_0, L(S_1)) = \delta(q_0, \{\}) = \{q_0\}$$

There is only one initial state (S_1, q_0)

The following is a fragment of $TS \otimes A$



The transitions were derived as follows:

$$S_1 \xrightarrow{\delta} S_2 \quad \delta(q_0, L(S_2)) = \delta(q_0, \{b, c\}) = \{q_1\}$$

$$S_2 \xrightarrow{\gamma} S_3 \quad \delta(q_1, L(S_3)) = \delta(q_1, \{e\}) = \{q_4\}$$

$$S_4 \xrightarrow{\beta} S_2 \quad \delta(q_4, L(S_2)) = \delta(q_4, \{\}) = \{q_3\}$$

Since (S_2, q_3) is reachable from the initial state we can conclude that

$$TS \not\models \varphi$$

The counterexample is given by the path

$$S_2 S_2 S_3 S_4 S_2 \text{ corresponding to the finite trace} \\ \{ \{ \{ b, c \} \{ e \} \{ b \} \{ \} \} \}.$$

Ex 4 First let us put the formula $\forall(a \cup \forall c)$ in existential normal form

$$\forall(a \cup \forall c)$$

$$\equiv \{ \forall \psi_1 \cup \psi_2 \equiv \neg \exists (\neg \psi_1 \cup (\neg \psi_1 \wedge \neg \psi_2)) \wedge \\ \neg \exists \square \neg \psi_2 \}$$

$$\neg \exists (\neg \forall \square c \cup (\neg a \wedge \neg \forall \square c)) \wedge \\ \neg \exists \square \neg \forall \square c$$

$$\equiv \{ \neg \forall \square \varphi \equiv \exists \square \neg \varphi \}$$

$$\neg \exists (\exists \square \neg c \cup (\neg a \wedge \exists \square \neg c)) \wedge$$

$$\neg \exists \square \exists \square \neg c \leftarrow \text{In E.N.F.}$$

$$\text{Sat}(\neg c) = S - \text{Sat}(c) = S - \{s_2, s_3, s_4\} = \\ = \{s_0, s_1\}$$

$$\text{Sat}(\neg a) = S - \text{Sat}(a) = S - \{s_0, s_2\} = \{s_1, s_3, s_4\}$$

$\text{Sat}(\exists \square \gamma_C)$ Calculation of a greatest fixpoint

$$\overline{T}_0 = \text{Sat}(\gamma_C) = \{s_0, s_1\}$$

$$\begin{aligned}\overline{T}_1 &= \overline{T}_0 - \{s \in S \mid \text{succ}(s) \cap \overline{T}_0 = \emptyset\} = \\ &= \overline{T}_0 - \{s_2\} = \{s_0\}\end{aligned}$$

$$\begin{aligned}\overline{T}_2 &= \overline{T}_1 - \{s \in S \mid \text{succ}(s) \cap \overline{T}_1 = \emptyset\} = \\ &= \overline{T}_1 - \{s_0\} = \{\} \quad \overline{T}_3 = \overline{T}_2\end{aligned}$$

$$\text{Thus, } \text{Sat}(\exists \square \gamma_C) = \{\}$$

$\text{Sat}(\exists \square (\exists \square \gamma_C))$. Since $\text{Sat}(\exists \square \gamma_C) = \{\}$

$$\text{then } \text{Sat}(\exists \square \{\}) = \{\}$$

$$\text{Sat}(\neg \exists \square (\exists \square \gamma_C)) = S - \text{Sat}(\exists \square (\exists \square \gamma_C)) =$$

$$S = \{s_0, s_1, s_2, s_3, s_4\}$$

$$\begin{aligned}\text{Sat}(\gamma_0 \wedge \exists \square \gamma_C) &= \text{Sat}(\gamma_0) \cap \text{Sat}(\exists \square \gamma_C) \\ &= \{s_2, s_3, s_4\} \cap \{\} = \{\}\end{aligned}$$

$\text{Sat}(\exists(\exists \Box_{\forall c} M \wedge \neg \exists \Box_{\forall c}))$.

Since $\text{Sat}(\exists \Box_{\forall c}) = \{\emptyset\}$ and $\text{Sat}(\neg \exists \Box_{\forall c}) = \emptyset$ then the \exists - M cannot be satisfied by any state. So the result is the empty set.

Thus

$\text{Sat}(\neg \exists(\exists \Box_{\forall c} M (\neg \exists \Box_{\forall c}))) =$

$$S - \{\emptyset\} = S = \{s_0, s_1, s_2, s_3, s_4\}$$

To conclude

$$\begin{aligned} & \text{Sat}(\neg \exists(\exists \Box_{\forall c} M (\neg \exists \Box_{\forall c}))) \\ & \quad \neg \exists \Box \exists \Box_{\forall c}) = S \cap S = S \end{aligned}$$
