

## Thread Libraries: POSIX threads (pthreads)

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- POSIX threads, pthreads;
- Solaris threads, sthreads.

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Creating a new thread...

A new thread is created via the function pthread\_create():

```
#include <pthread.h>
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int pthread_create(
    pthread_t *tid,
    const pthread_attr_t *tattr,
    void*(*start_routine)(void *),
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```

- tid stores the thread ID;
- tattr is used to change the default thread attributes of the newly created thread (often is NULL);
- start\_routine is the function executed by the new thread;
- arg refers to the arguments passed to start\_routine ;
- pthread\_create returns zero when it completes successfully.

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Wait for Thread Termination...



To wait termination of a thread, functions <code>pthread\_join</code> and <code>pthread\_join</code> can be used:

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#include <pthread.h>
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int pthread_join(thread_t tid, void **status);
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```

The specified thread must be in the current process and must not be detached (see below).

When status is not NULL, it points to a location that is set to the exit status of the terminated thread.

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#### POSIX Threads Library Thread specific storage...



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Function pthread\_keycreate is called once for each key before the key is used:

```
int pthread_key_create(
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    void (*destructor) (void *)
);
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Function pthread\_keycreate is called once for each key before the key is used:

```
int pthread_key_create(
    pthread_key_t *key,
    void (*destructor) (void *)
);
```

Zero is returned after the operations has been completed successfully. Any other returned value indicates that an error occurred.



The following functions can be used to manage values in the TSD: int pthread\_key\_delete(pthread\_key\_t key);

void \*pthread\_getspecific(pthread\_key\_t key);

#### Example: Usage of TSD



Thread identifier...



The function  $\ensuremath{\mathsf{pthread\_self}}$  () can be called to return the ID of the calling thread:

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Function pthread\_equal() can be used to compare two thread ids: int pthread\_equal(pthread\_t tid1, pthread\_t tid2);

Terminating threads. . .

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- A thread can terminate its execution in the following ways:
  - By returning from its first (outermost) procedure, the threads start routine;
  - By calling pthread\_exit (), supplying an exit status;
  - By termination with POSIX cancel functions pthread\_cancel().

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- By termination with POSIX cancel functions pthread\_cancel().

```
void pthread_exit(void *status)
```

```
int pthread_cancel(pthread_t thread)
```

Thread Synchronisation...



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- Condition Variables
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A synchronization objects is a variable used by threads to interact with each other.

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Thread synchronisation is needed when:

- it is the only way to ensure consistency of shared data.
- two or more threads can use a single synchronisation object jointly.
- we have to ensure the safety of mutable data.
- when there is a race.



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Mutex locks can also preserve single-threaded code.





Mutexes are represented by the  ${\tt pthread\_mutex\_t}$  object.

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Although you can dynamically create mutexes, most uses are static:

```
/* define and initialize a mutex named 'mutex' */
pthread_mutex_t mutex = PTHREAD_MUTEX_INITIALIZER;
```



Locking (also called acquiring) a Pthreads mutex is accomplished via the pthread\_mutex\_lock() function:

#include <pthread.h>

int pthread\_mutex\_lock (pthread\_mutex\_t \*mutex);



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#include <pthread.h>

int pthread\_mutex\_lock (pthread\_mutex\_t \*mutex);

A successful call to pthread\_mutex\_lock() will block the calling thread until the mutex pointed at by mutex becomes available.



#### The counterpart to locking is unlocking, or releasing, the mutex: #include <pthread.h>

int pthread\_mutex\_unlock (pthread\_mutex\_t \*mutex);



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A successful call to  $pthread_mutex\_unlock()$  releases the mutex pointed at by mutex and returns zero.



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int pthread_mutex_unlock (pthread_mutex_t *mutex);
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A successful call to  ${\tt pthread\_mutex\_unlock}()$  releases the mutex pointed at by mutex and returns zero.

The call does not block; the mutex is released immediately.

### Example: Using mutexes



static pthread\_mutex\_t the\_mutex = PTHREAD\_MUTEX\_INITIALIZER;

```
int withdraw (struct account *account, int amount)
{
    pthread_mutex_lock (&the_mutex);
    const int balance = account->balance;
    if (balance < amount) {
        pthread_mutex_unlock (&the_mutex);
        return -1;
    }
    account->balance = balance - amount;
    pthread_mutex_unlock (&the_mutex);
    disburse_money (amount);
    return 0;
```



#### To be continued...

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### GNU Make

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You can issue make ——help to list the command-line options; or man make to display the man pages.



Let's begin with a simple example to build the Hello-world program (hello.c) into executable (hello) via make utility.



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```
// hello.c
#include <stdio.h>
int main() {
    printf("Hello, world!\n");
    return 0;
}
```

## First Makefile By Example

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The following file named makefile contains all the rules needed to build the executable:

```
all: hello
hello: hello.o
gcc -o hello hello.o
hello.o: hello.c
gcc -c hello.c
clean:
rm hello.o hello
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```

This file must be in the same directory of your sources.

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  - and a command.

A rule has the following form:

```
target: pre-req-1 pre-req-2 ... command
```

The target and pre-requisites are separated by a colon (:). The command must be preceded by a tab (**NOT spaces!!**).



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A general syntax for the rules is:

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The standard phony targets are: all, clean, install.

#### Makefile: Variables



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Automatic variables are set by make after a rule is matched. There include:

- **\$**@: the target filename.
- **\$**\*: the target filename without the file extension.
- **\$**<: the first prerequisite filename.
- \$^: the filenames of all the prerequisites, separated by spaces, discard duplicates.
- \$+: similar to \$^, but includes duplicates.
- \$?: the names of all prerequisites that are newer than the target, separated by spaces.

Example...



all: hello hello: hello.o gcc -o \$@ \$< hello.o: hello.c gcc -c \$< clean: rm hello.o hello

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#### Virtual paths...



We can use VPATH (uppercase) to specify the directory to search for dependencies and target files.

# Search for dependencies and targets from "src" and "include " directories # The directories are separated by space VPATH = src include



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```
# Search for dependencies and targets from "src" and "include
    " directories
# The directories are separated by space
VPATH = src include
```

We can also use  $\mathsf{vpath}$  (lowercase) to be more precise about the file type and its search directory

```
# Search for .c files in "src" directory;
# .h files in "include" directory
# The pattern matching character '%' matches filename without
the extension
vpath %.c src
vpath %.h include
```



A pattern rule, which uses pattern matching character '%' as the filename, can be applied to create a target, if there is no explicit rule.

```
# Applicable for create .o object file.
# '%' matches filename.
# $< is the first pre-requisite
# $(COMPILE.c) consists of compiler name and compiler options
# $(OUTPUT_OPTIONS) could be -o $@
%.o: %.c
$(COMPILE.c) $(OUTPUT_OPTION) $<</pre>
```

```
# Applicable for create executable (without extension)
# from object .o object file
# $^ matches all the pre-requisites (no duplicates)
%: %.0
f(UNI(-)) f^ f(UOADUDES) f(UDUDES)
```

```
$(LINK.o) $^ $(LOADLIBES) $(LDLIBS) -o $@
```



#### To be continued...

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GNU Make

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